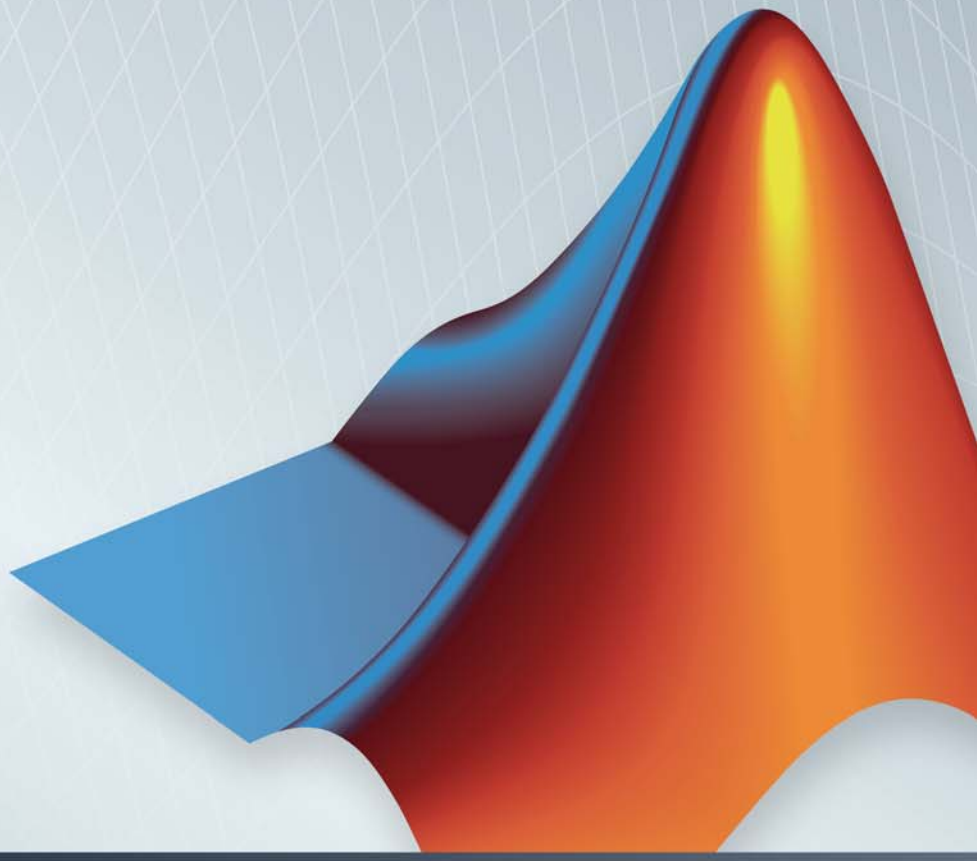
HDL Verifier™

Reference

R2013a



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HDL Verifier™ Reference

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September 2012	Online only	Revised for Version 4.1 (Release 2012b)
March 2013	Online only	Revised for Version 4.2 (Release 2013a)

Contents

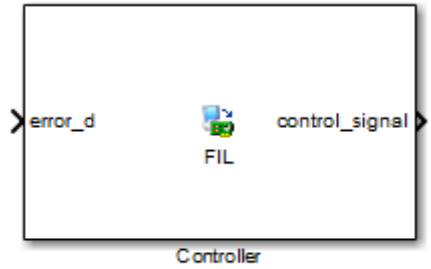
1

Blocks — Alphabetical List

FIL Simulation

Purpose

Simulate HDL code on FPGA hardware from Simulink



Description

Example of FIL Block Generated From HDL Code

The generated FIL simulation block is the communication interface between the FPGA and your Simulink® model. It integrates the hardware into the simulation loop and allows it to participate in simulation as any other block.

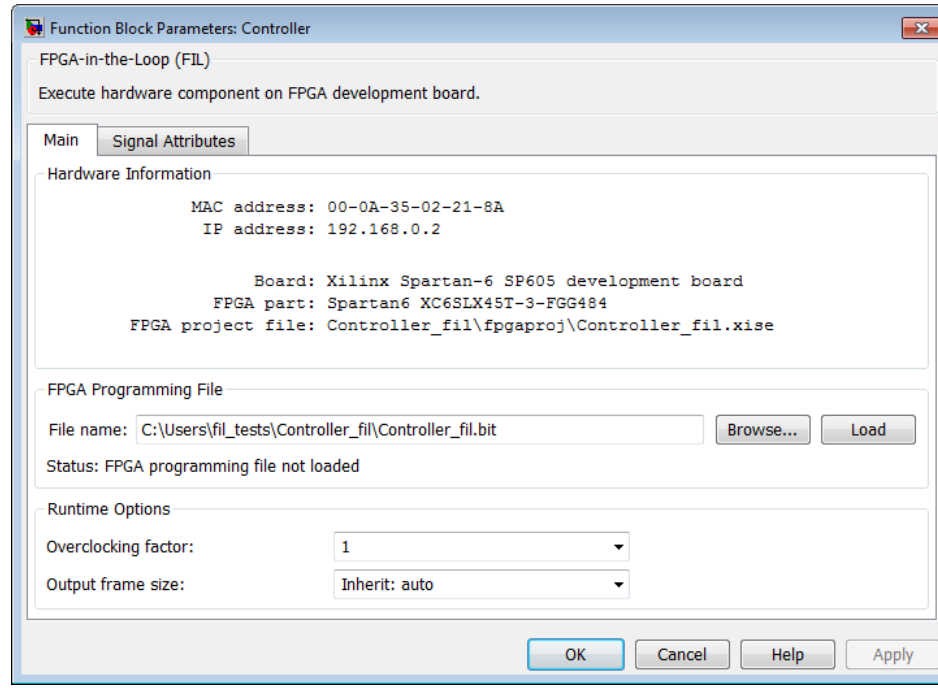
You can perform FIL simulation with the instructions found in "Performing FPGA-in-the-Loop Simulation". If you encounter any issues during FIL simulation, refer to "Troubleshooting FIL" for help in diagnosing the problem.

Dialog Box

Use the FIL block mask to perform the following tasks:

- Download the generated FPGA programming file onto the FPGA. You must perform this step before you can run a FIL simulation. (See "Load Programming File onto FPGA".)
- Adjust FIL block settings (optional). See the sections for "Main" on page 1-3 and "Signal Attributes" on page 1-4.

Main



Example of FIL Block Mask Main Tab (Generated From HDL Code)

On the **Main** tab, you have the following options:

- Download FPGA programming file.

  You can verify that the file name in FPGA programming file name is as you expected; if it is not, you can change it here. If you have no other changes to the block mask, you can click Load to initiate the download.

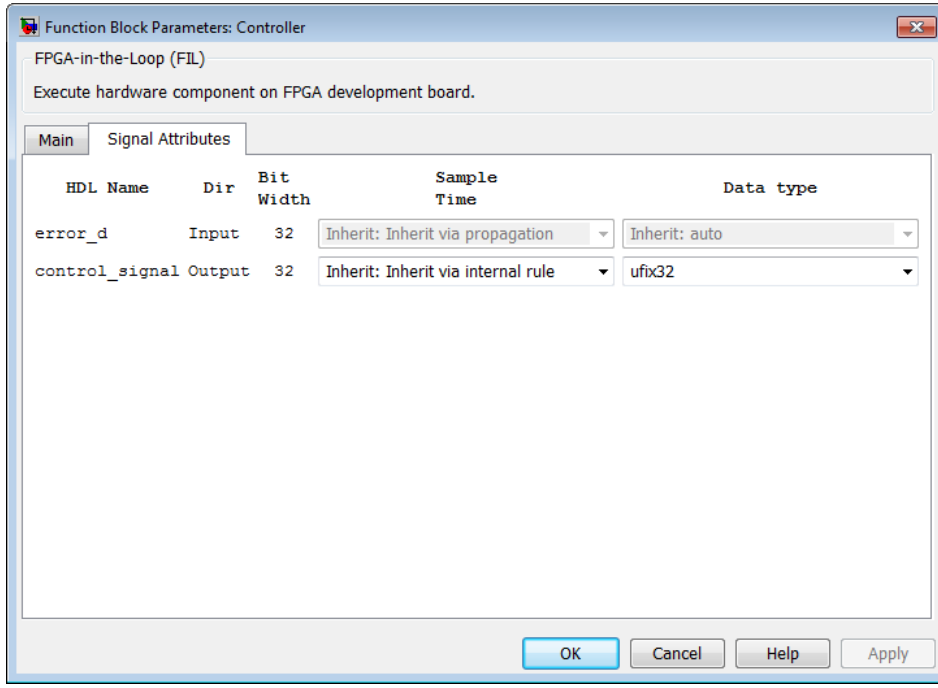
- Change output frame size for the current FIL simulation.

Under **Runtime Options**, for the **Output frame size** option, specify the output frame size as an expression, variable, or function, or specify `Inherit: auto`.

- Change HDL overclocking factor for the current FIL simulation.

  Under **Runtime Options**, for the **Overclocking Factor** option, select `Inherit: auto` or enter an expression, variable, or function. This setting specifies that an input value is sampled *x* times by the FPGA clock before the input changes value, where *x* is the value you entered in this field.

Signal Attributes



Example of FIL Block Mask Signal Attributes Tab (Generated From HDL Code)

On the **Signal Attributes** tab, you have the following options:

- Change output sample times.

  You may explicitly set sample times or use `Inherit: internal rule`. The internal rule is to set the output sample times to the input base sample time divided by the scaling factor.

- Change output data types.

  You may explicitly set data types, use the default of an unscaled and unsigned data type, or specify `Inherit: auto` to inherit a data type from the block's context.

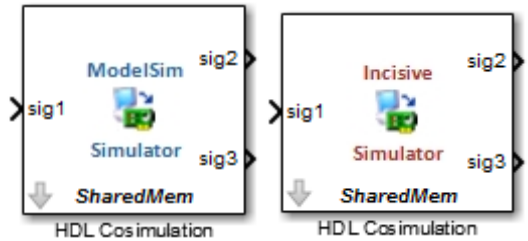
HDL Cosimulation

Purpose

Cosimulate hardware component by communicating with HDL module instance executing in HDL simulator

Library

HDL Verifier



Description

The HDL Cosimulation block cosimulates a hardware component by applying input signals to and reading output signals from an HDL model under simulation in the HDL simulator. You can use this block to model a source or sink device by configuring the block with input or output ports only.

The tabbed panes on the block's dialog box let you configure:

- Block input and output ports that correspond to signals (including internal signals) of an HDL module. You must specify a sample time for each output port; you can also specify a data type for each output port.
- Type of communication and communication settings used to exchange data between simulators.
- The timing relationship between units of simulation time in Simulink and the HDL simulator.
- Rising-edge or falling-edge clocks to apply to your model. You can specify the period for each clock signal.
- Tcl commands to run before and after the simulation.

Compatibility with Simulink® Code Generation

- HDL Coder™: The HDL Verifier™ HDL Cosimulation block does participate in code generation with HDL Coder.
- Simulink Coder™: The HDL Verifier HDL Cosimulation block does not participate in code generation with Simulink Coder for C code generation.

The HDL Cosimulation Block Panes

The **Ports** pane provides fields for mapping signals of your HDL design to input and output ports in your block. The signals can be at any level of the HDL design hierarchy.

The **Timescales** pane lets you choose an optimal timing relationship between Simulink and the HDL simulator. You can configure either of the following timing relationships:

- *Relative* timing relationship (Simulink seconds correspond to an HDL simulator-defined tick interval)
- *Absolute* timing relationship (Simulink seconds correspond to an absolute unit of HDL simulator time)

The **Connection** pane specifies the communications mode used between Simulink and the HDL simulator. If you use TCP socket communication, this pane provides fields for specifying a socket port and for the host name of a remote computer running the HDL simulator. The **Connection** pane also provides the option for bypassing the cosimulation block during Simulink simulation.

The **Clocks** pane lets you create optional rising-edge and falling-edge clocks that apply stimuli to your cosimulation model.

The **Simulation** pane provides a way of specifying tools command language (Tcl) commands to be executed before and after the HDL

simulator simulates the HDL component of your Simulink model. You can use the **Pre-simulation commands** field on this pane for simulation initialization and startup operations, but you cannot use it to change simulation state.

Note You must make sure that signals being used in cosimulation have read/write access. This rule applies to all signals on the **Ports**, **Clocks**, and **Simulation** panes. Verify such access through the HDL simulator—see product documentation for details.

Dialog Box

The Block Parameters dialog box consists of the following tabbed panes of configuration options:

Ports Pane

Specify fields for mapping signals of your HDL design to input and output ports in your block. Simulink deposits an input port signal on an HDL simulator signal at the signal's sample rate. Conversely, Simulink reads an output port signal from a specified HDL simulator signal at the specified sample rate.

In general, Simulink handles port sample periods as follows:

- If you connect an input port to a signal that has an explicit sample period, based on forward propagation, Simulink applies that rate to the port.
- If you connect an input port to a signal that does not have an explicit sample period, Simulink assigns a sample period that is equal to

the least common multiple (LCM) of all identified input port sample periods for the model.

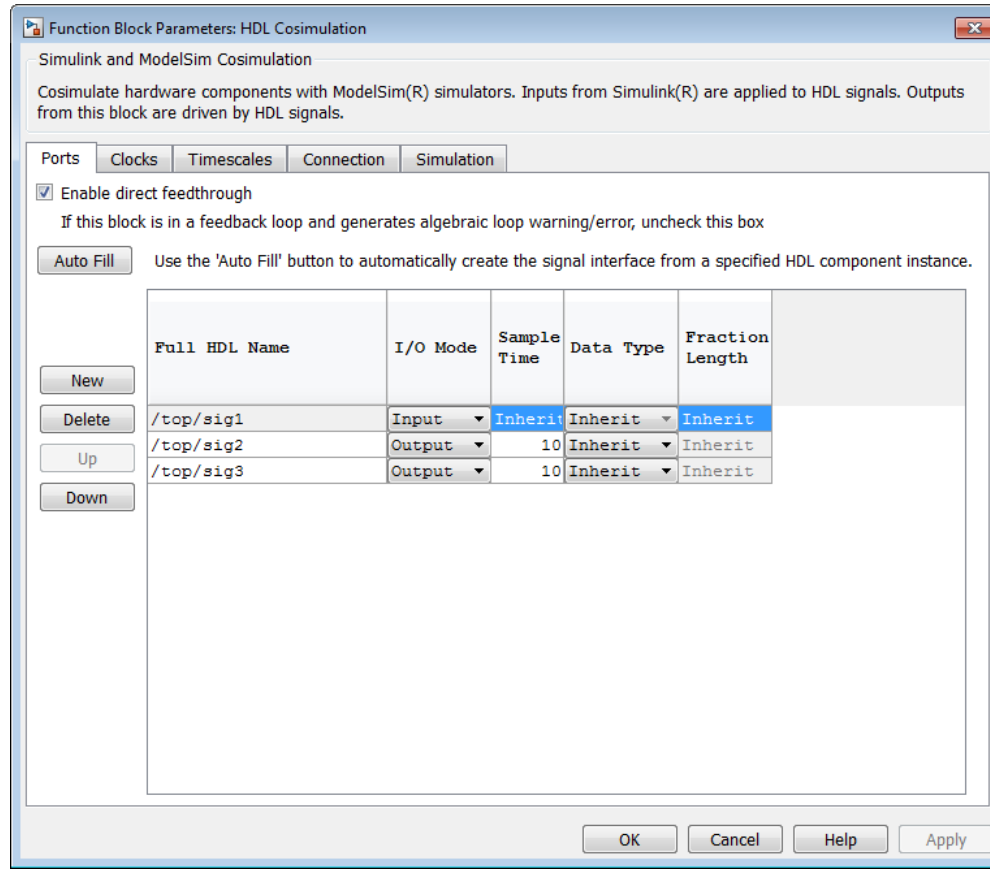
- After Simulink sets the input port sample periods, it applies user-specified output sample times to all output ports. You must specify an explicit sample time for each output port.

In addition to specifying output port sample times, you can force the fixed-point data types on output ports. For example, setting the **Data Type** property of an 8-bit output port to `Signed` and setting its **Fraction Length** property to `5` would force the data type to `sfix8_En5`. You can not force width; the width is always inherited from the HDL simulator.

Note The **Data Type** and **Fraction Length** properties apply only to the following signals:

- VHDL signals of any logic type, such as`STD_LOGIC` or `STD_LOGIC_VECTOR`
- Verilog signals of `wire` or `reg` type

You can set input/output ports in the **Ports** pane also. To do so, specify port as both input and output (example shown for use with ModelSim).



If your model contains purely combinational paths, you can select **Enable direct feedthrough for HDL design with pure combinational datapath** to eliminate the one output-sample delay that occurs with using HDL Verifier blocks and Simulink. For more information on block simulation latency and using the direct feedthrough feature to eliminate it, see “Direct Feedthrough Cosimulation”.

The list at the center of the pane displays HDL signals corresponding to ports on the HDL Cosimulation block. Maintain this list with the buttons on the left of the pane:

- **Auto Fill** — Transmit a port information request to the HDL simulator. The port information request returns port names and information from an HDL model (or module) under simulation in the HDL simulator and automatically enters this information into the ports list. See "Obtaining Signal Information from the HDL Simulator" for a detailed description of this feature.
- **New** — Add a new signal to the list and select it for editing.
- **Delete** — Remove a signal from the list.
- **Up** — Move the selected signal up one position in the list.
- **Down** — Move the selected signal down one position in the list.

To commit edits to the Simulink model, you must also click **Apply** after selecting parameter values.

Note When you import VHDL signals from the HDL simulator , HDL Verifier returns the signal names in all capitals.

To edit a signal name, double-click on the name. Set the signal properties on the same line and in the associated columns. The properties of a signal are as follows.

Full HDL Name

Specifies the signal path name, using the HDL simulator path name syntax. For example (for use with Incisive), a path name for an input port might be `manchester.samp`. The signal can be at any level of the HDL design hierarchy. The HDL Cosimulation block port corresponding to the signal is labeled with the **Full HDL Name**.

For rules on specifying signal/port and module path specifications in Simulink, see "Specifying HDL Signal/Port and Module Paths for Cosimulation".

Copying Signal Path Names You can copy signal path names directly from the HDL simulator **wave** window and paste them into the **Full HDL Name** field, using the standard copy and paste commands in the HDL simulator and Simulink. You must use the Path.Name view and not Db::Path.Name view. After pasting a signal path name into the **Full HDL Name** field, you must click the **Apply** button to complete the paste operation and update the signal list.

I/O Mode

Select either `Input`, `Output`, or both.

`Input` designates signals of your HDL module that Simulink will drive. Simulink deposits values on the specified the HDL simulator signal at the signal's sample rate.

Note When you define a block input port, make sure that only one source is set up to drive input to that signal. For example, you should avoid defining an input port that has multiple instances. If multiple sources drive input to a single signal, your simulation model may produce unexpected results.

`Output` designates signals of your HDL module that Simulink will read. For output signals, you must specify an explicit sample time. You can also specify any data type (except width). For details on specifying a data type, see Date Type and Fraction Length in a following section.

Because Simulink signals do not have the semantic of tri-states (there is no 'Z' value), you will gain no benefit by connecting to a bidirectional HDL signal directly. To interface with bidirectional signals, you can first interface to the input of the output driver, then the enable of the output driver and the output of the input driver. This approach leaves the actual tri-state buffer in HDL where resolution functions can handle interfacing with other tri-state buffers.

Sample Time

This property becomes available only when you specify an output signal. You must specify an explicit sample time.

Sample Time represents the time interval between consecutive samples applied to the output port. The default sample time is `1`. The exact interpretation of the output port sample time depends on the settings of the **Timescales** pane of the HDL Cosimulation block. See also "Simulation Timescales".

Data Type
Fraction Length

These two related parameters apply only to output signals.

The **Data Type** property is enabled only for output signals. You can direct Simulink to determine the data type, or you can assign an explicit data type (with option fraction length). By explicitly assigning a data type, you can force fixed-point data types on output ports of an HDL Cosimulation block.

The **Fraction Length** property specifies the size, in bits, of the fractional part of the signal in fixed-point representation. **Fraction Length** becomes available if you do not set the **Data Type** property to `Inherit`.

The data type specification for an output port depends on the signal width and by the **Data Type** and **Fraction Length** properties of the signal.

Note The **Data Type** and **Fraction Length** properties apply only to the following signals:

- VHDL signals of any logic type, such as `STD_LOGIC` or `STD_LOGIC_VECTOR`
- Verilog signals of `wire` or `reg` type

To assign a port data type, set the **Data Type** and **Fraction Length** properties as follows:

- Select `Inherit` from the **Data Type** list if you want Simulink to determine the data type.

  This property defaults to`Inherit`. When you select `Inherit`, the **Fraction Length** edit field becomes unavailable.

  Simulink always double checks that the word-length back propagated by Simulink matches the word length queried from the HDL simulator. If they do not match, Simulink generates an error message. For example, if you connect a Signal Specification block to an output, Simulink will force the data type specified by Signal Specification block on the output port.

  If Simulink cannot determine the data type of the signal connected to the output port, it will query the HDL simulator for the data type of the port. As an example, if the HDL simulator returns the VHDL data type `STD_LOGIC_VECTOR` for a signal of size `N` bits, the data type `ufixN` is forced on the output port. (The implicit fraction length is 0.)

- Select `Signed` from the **Data Type** list if you want to explicitly assign a signed fixed point data type. When you select`Signed`, the **Fraction Length** edit field becomes available. HDL Verifier assigns the port a fixed-point type `sfixN_EnF`, where `N` is the signal width and `F` is the **Fraction Length**.

  For example, if you specify **Data Type** as `Signed` and a **Fraction Length** of `5` for a 16-bit signal, Simulink forces the

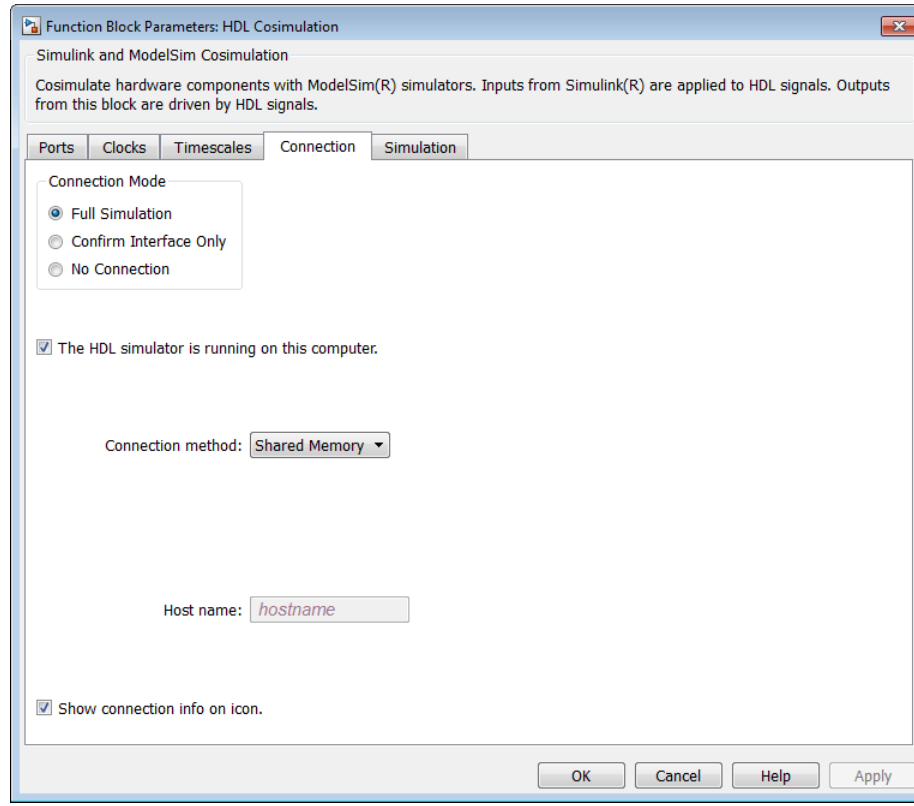
data type to `sfix16_En5`. For the same signal with a **Data Type** set to `Signed` and **Fraction Length** of `-5`, Simulink forces the data type to `sfix16_E5`.

- Select `Unsigned` from the **Data Type** list if you want to explicitly assign an unsigned fixed point data type When you select`Unsigned`, the **Fraction Length** edit field becomes available. HDL Verifier assigns the port a fixed-point type `ufixN_EnF`, where `N` is the signal width and `F` is the **Fraction Length**.

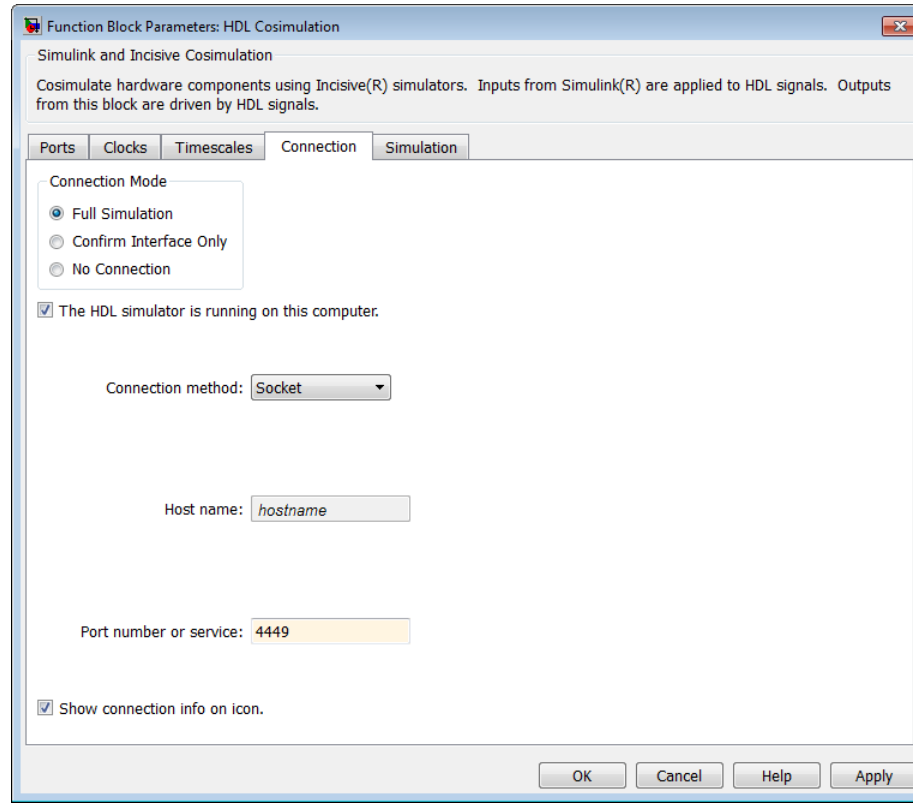
  For example, if you specify **Data Type** as `Unsigned` and a **Fraction Length** of `5` for a 16-bit signal, Simulink forces the data type to `ufix16_En5`. For the same signal with a **Data Type** set to `Unsigned` and **Fraction Length** of `-5` , Simulink forces the data type to `ufix16_E5`.

Connection Pane

This figure shows the default configuration of the **Connection** pane (example shown is for use with Incisive). The block defaults to a shared memory configuration for communication between Simulink and the HDL simulator, when they run on a single computer.



If you select TCP/IP socket mode communication, the pane displays additional properties, as shown in the following figure.



Connection Mode

If you want to bypass the HDL simulator when you run a Simulink simulation, use these options to specify what type of simulation connection you want. Select one of the following options:

- **Full Simulation**: Confirm interface and run HDL simulation (default).
- **Confirm Interface Only**: Connect to the HDL simulator and check for signal names, dimensions, and data types, but do not run HDL simulation.

- **No Connection**: Do not communicate with the HDL simulator. The HDL simulator does not need to be started.

With the second and third options, the HDL Verifier cosimulation interface does not communicate with the HDL simulator during Simulink simulation.

The HDL Simulator is running on this computer
Select this option if you want to run Simulink and the HDL simulator on the same computer. When both applications run on the same computer, you have the choice of using shared memory or TCP sockets for the communication channel between the two applications. If you do not select this option, only TCP/IP socket mode is available, and the **Connection method** list becomes unavailable.

Connection method
This list becomes available when you select**The HDL Simulator is running on this computer**. Select `Socket` if you want Simulink and the HDL simulator to communicate via a designated TCP/IP socket. Select `Shared memory` if you want Simulink and the HDL simulator to communicate via shared memory. For more information on these connection methods, see "Communications for HDL Cosimulation".

Host name
If you run Simulink and the HDL simulator on different computers, this text field becomes available. The field specifies the host name of the computer that is running your HDL simulation in the HDL simulator.

Port number or service
Indicate a valid TCP socket port number or service for your computer system (if not using shared memory). For information on choosing TCP socket ports, see "Choosing TCP/IP Socket Ports".

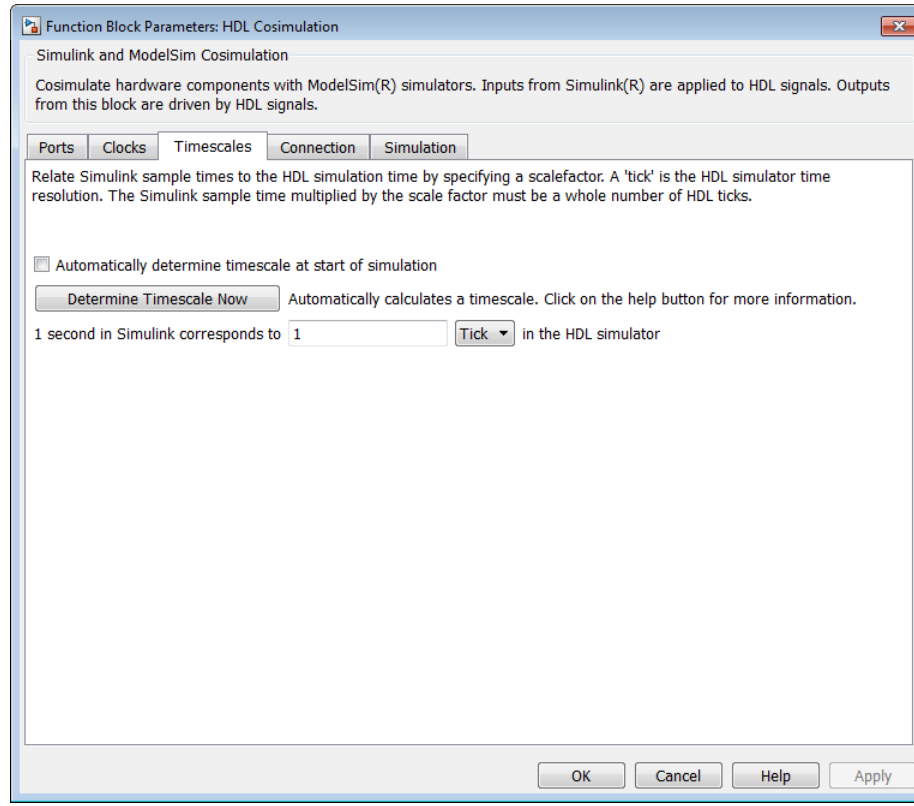
Show connection info on icon
When you select this option, Simulink indicates information about the selected communication method and (if applicable)

communication options information on the HDL Cosimulation block icon. If you select shared memory, the icon displays the string `SharedMem`. If you select TCP socket communication, the icon displays the string **Socket** and displays the host name and port number in the format `hostname:port`.

In a model that has multiple HDL Cosimulation blocks, with each communicating to different instances of the HDL simulator in different modes, this information helps to distinguish between different cosimulation sessions.

Timescales Pane

The **Timescales** pane of the HDL Cosimulation block parameters dialog box lets you choose a timing relationship between Simulink and the HDL simulator, either manually or automatically. The following figure shows the default settings of the **Timescales** pane (example shown for use with ModelSim®).



The **Timescales** pane specifies a correspondence between one second of Simulink time and some quantity of HDL simulator time. This quantity of HDL simulator time can be expressed in one of the following ways:

- Using *relative timing mode*. HDL Verifier defaults to relative timing mode.
- Using *absolute timing mode*

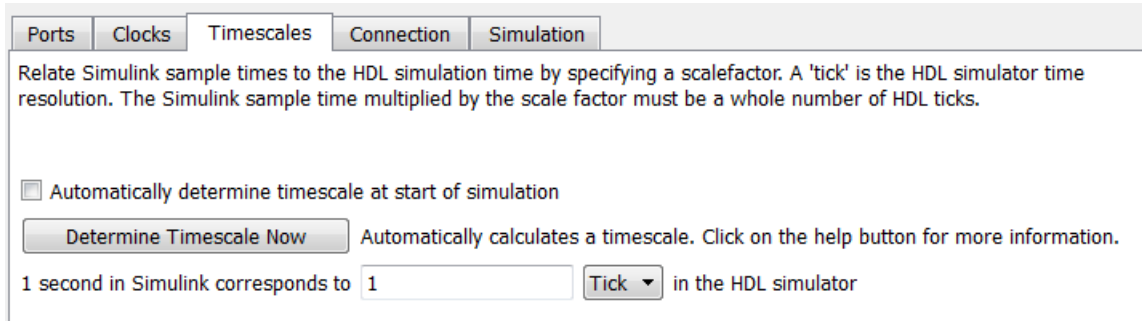
For more information on calculating relative and absolute timing modes, see “Defining the Simulink and HDL Simulator Timing Relationship”.

For detailed information on the relationship between Simulink and the HDL simulator during cosimulation, and on the operation of relative and absolute timing modes, see “Simulation Timescales”.

The following sections describe how to specify the timing relationship, either automatically or manually.

Automatically Specifying the Timing Relationship

To have the HDL Verifier software calculate the timing relationship for you, perform the following steps and enter any applicable information in the **Timescales** pane (as shown in the following figure).

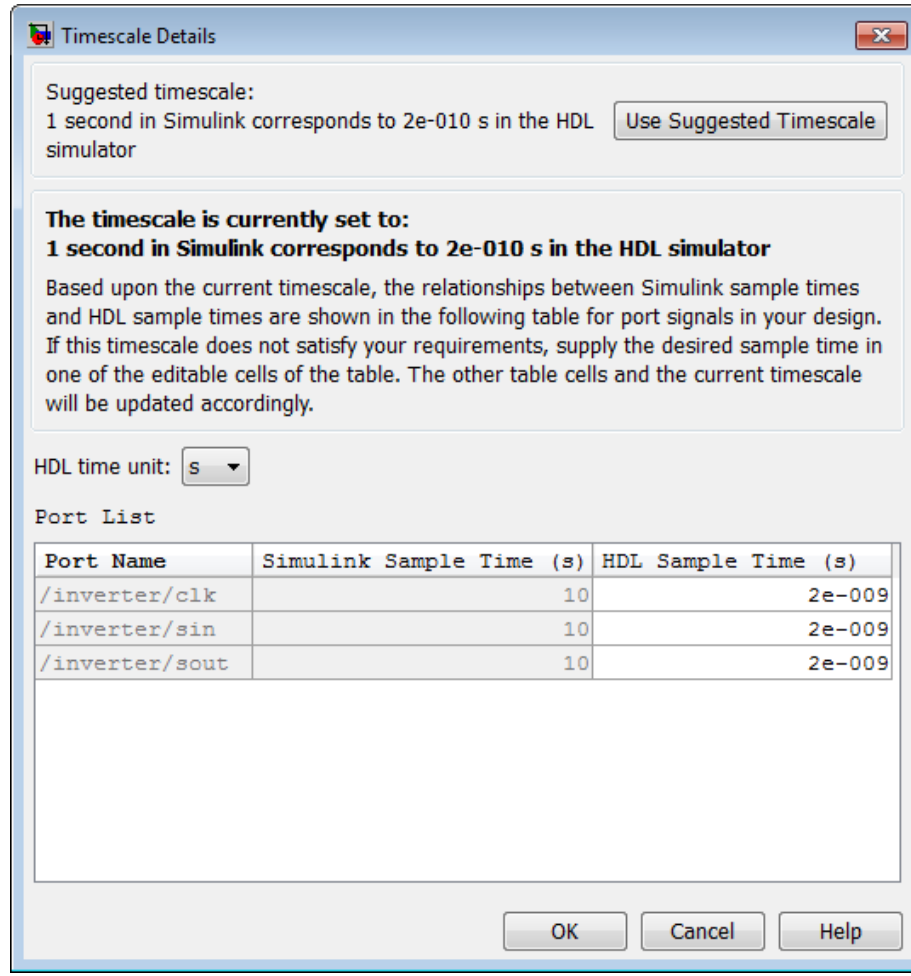


1. Verify that the HDL simulator is running. HDL Verifier software can obtain the resolution limit of the HDL simulator only when that simulator is running.

2. Choose whether you want to have HDL Verifier software suggest a timescale at this time or if you want to have the software perform this calculation when the simulation begins in Simulink.

   - To have the calculation performed while you are configuring the block, click the **Timescale** option, and then click **Determine Timescale Now**. The software connects Simulink with the HDL simulator so that Simulink can use the HDL simulator resolution to calculate the best timescale. The link then displays those results to you in the **Timescale Details** dialog box.

Note For the results to display, make sure the HDL simulator is running and the design loaded for cosimulation. The simulation does not have to be running.



You can accept the timescale the software suggests, or you can make changes in the port list directly:

- If you want to revert to the originally calculated settings, click **Use Suggested Timescale**.
- If you want to view sample times for all ports in the HDL design, select **Show all ports and clocks**.

- To have the calculation performed when the simulation begins, select **Automatically determine timescale at start of simulation**, and click **Apply**. You obtain the same **Timescale Details** dialog box when the simulation starts in Simulink.

Note For the results to display, make sure the HDL simulator is running and the design loaded for cosimulation. The simulation does not have to be running.

HDL Verifier software analyzes all the clock and port signal rates from the HDL Cosimulation block when the software calculates the scale factor.

Note HDL Verifier software cannot automatically calculate a sample timescale based on any signals driven via Tcl commands or in the HDL simulator. The link software cannot perform such calculations because it cannot know the rates of these signals.

The link software returns the sample rate in either seconds or ticks:

- If the results are in seconds, then the link software was able to resolve the timing differences in favor of fidelity (absolute time).
- If the results are in ticks, then the link software was best able to resolve the timing differences in favor of efficiency (relative time).

Each time you select **Determine Timescale Now** or **Automatically determine timescale at start of simulation**, the HDL Verifier software opens an interactive display. This display explains the results of the timescale calculations. If the link software cannot calculate a timescale for the given sample times, adjust your sample times in the **Port List**.

3 Click **Apply** to commit your changes.

Note HDL Verifier does not support timescales calculated automatically from frame-based signals.

For more on the timing relationship between the HDL simulator and Simulink, see "Simulation Timescales".

Manually Specifying a Relative Timing Relationship

To manually configure relative timing mode for a cosimulation, perform the following steps:

1 Select the **Timescales** tab of the HDL Cosimulation block parameters dialog box.

2 Verify that `Tick`, the default setting, is selected. If it is not, then select it from the list on the right.

3 Enter a scale factor in the text box on the left. The default scale factor is 1. For example, the next figure, shows the **Timescales** pane configured for a relative timing correspondence of 10 HDL simulator ticks to 1 Simulink second.

4 Click **Apply** to commit your changes.

Manually Specifying an Absolute Timing Relationship

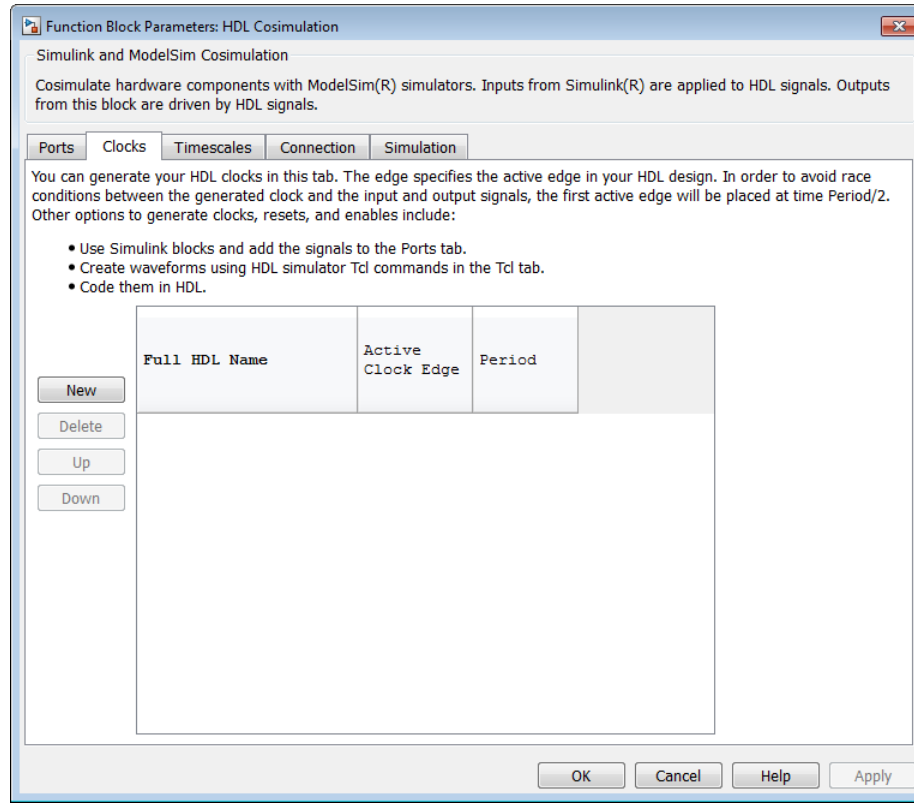
To manually configure absolute timing mode for a cosimulation, perform the following steps:

1. Select the **Timescales** tab of the HDL Cosimulation block parameters dialog box.
2. Select a unit of absolute time from the list on the right. The units available include `fs` (femtoseconds), `ps` (picoseconds), `ns` (nanoseconds), `us` (microseconds), `ms` (milliseconds), and `s` (seconds).
3. Enter a scale factor in the text box on the left. The default scale factor is 1. For example, in the next figure, the **Timescales** pane is configured for an absolute timing correspondence of 1 HDL simulator second to 1 Simulink second.

4. Click **Apply** to commit your changes.

Clocks Pane

You can create optional rising-edge and falling-edge clocks that apply stimuli to your cosimulation model. To do so, use the Clocks pane of the HDL Cosimulation block.



The scrolling list at the center of the pane displays HDL clocks that drive values to the HDL signals that you are modeling, using the deposit method.

Maintain the list of clock signals with the buttons on the left of the pane:

- **New** — Add a new clock signal to the list and select it for editing.
- **Delete** — Remove a clock signal from the list.
- **Up** — Move the selected clock signal up one position in the list.
- **Down** — Move the selected clock signal down one position in the list.

To commit edits to the Simulink model, you must also click **Apply**.

A clock signal has the following properties.

Full HDL Name

Specify each clock as a signal path name, using the HDL simulator path name syntax. For example: `/manchester/clk` or `manchester.clk`.

For information about and requirements for path specifications in Simulink, see "Specifying HDL Signal/Port and Module Paths for Cosimulation".

Note You can copy signal path names directly from the HDL simulator **wave** window and paste them into the **Full HDL Name** field, using the standard copy and paste commands in the HDL simulator and Simulink. You must use the Path.Name view and not Db::Path.Name view. After pasting a signal path name into the **Full HDL Name** field, you must click the **Apply** button to complete the paste operation and update the signal list.

Edge

Select `Rising` or `Falling` to specify either a rising-edge clock or a falling-edge clock.

Period

You must either specify the clock period explicitly or accept the default period of `2`.

If you specify an explicit clock period, you must enter a sample time equal to or greater than 2 resolution units (ticks).

If the clock period (whether explicitly specified or defaulted) is not an even integer, Simulink cannot create a 50% duty cycle. Instead, the HDL Verifier software creates the falling edge at

clockperiod / 2

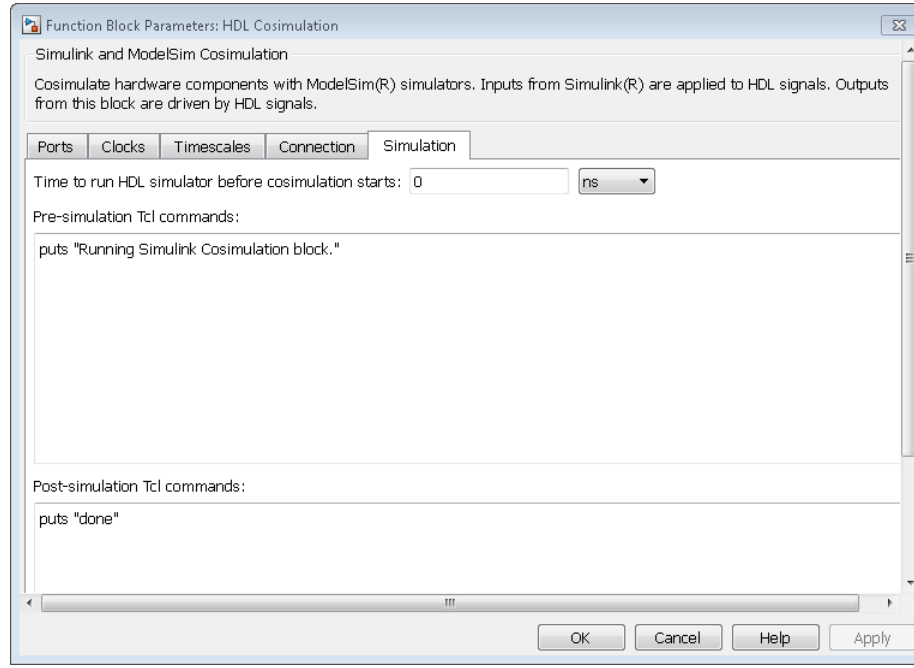
(rounded down to the nearest integer).

Note The **Clocks** pane does not support vectored signals. Signals must be logic types with 1 and 0 values.

For instructions on adding and editing clock signals, see "Creating Optional Clocks with the Clocks Pane of the HDL Cosimulation Block".

Simulation Pane

Specify tools command language (Tcl) commands to be executed before and after the HDL simulator simulates the HDL component of your Simulink model (example shown for use with ModelSim).



You may specify any valid Tcl command string. The Tcl command string you specify cannot include commands that load an HDL simulator project or modify simulator state. For example, the string cannot include commands such as `start`, `stop`, or `restart` (for ModelSim) or `run`, `stop`, or `reset` (for Incisive).

Time to run HDL simulator before cosimulation starts:
Specifies the amount of time to run the HDL simulator before beginning simulation in Simulink.

This setting consists of a *PreRunTime* value and a *PreRunTimeUnit* value.

- PreRunTime: Any valid time value. The default is 0.
- PreRunTimeUnit: Specifies the units of time for PreRunTime. You can select one of:
  - `Tick`
  - `s`
  - `ms`
  - `us`
  - `ns`
  - `ps`
  - `fs`

This parameter allows HDL Verifier properly align the signal of your behavioral block and the HDL signal so that they can be compared and verified directly without additional delays.

Pre-simulation commands
Contains Tcl commands to be executed before the HDL simulator simulates the HDL component of your Simulink model. You can specify one Tcl command per line in the text box or enter multiple commands per line by appending each command with a semicolon (;), the standard Tcl concatenation operator.

Use of this field can range from something as simple as a one-line echo command to confirm that a simulation is running to a complex script that performs an extensive simulation initialization and startup sequence.

Post-simulation commands
Contains Tcl commands to be executed after the HDL simulator simulates the HDL component of your Simulink model. You can specify one Tcl command per line in the text box or enter multiple commands per line by appending each command with a semicolon (;), the standard Tcl concatenation operator.

Note for ModelSim Users After each simulation, it takes ModelSim time to update the coverage result. To prevent the potential conflict between this process and the next cosimulation session, add a short pause between each successive simulation.

Creating a Tcl Script as an Alternative to Using the Simulation Pane

You can create a Tcl script that lists the Tcl commands you want to execute on the HDL simulator, either pre- or post-simulation.

Tcl Scripts for ModelSim Users

You can create a ModelSim DO file that lists Tcl commands and then specify that file with the ModelSim `do` command as follows:

```
do mycosimstartup.do
```

Or

```
do mycosimcleanup.do
```

You can include the `quit -f` command in an after-simulation Tcl command string or DO file to force ModelSim to shut down at the end of a cosimulation session. Specify all after simulation Tcl commands in

a single cosimulation block and place `quit` at the end of the command string or DO file.

With the exception of `quit`, the command string or DO file that you specify cannot include commands that load a ModelSim project or modify simulator state. For example, they cannot include commands such as `start`, `stop`, or `restart`.

Tcl Scripts for Incisive Users

You can create an HDL simulator Tcl script that lists Tcl commands and then specify that file with the HDL simulator `source` command as follows:

```
source mycosimstartup.script_extension
```

Or

```
source mycosimcleanup.script_extension
```

You can include the `exit` command in an after-simulation Tcl script to force the HDL simulator to shut down at the end of a cosimulation session. Specify all after simulation Tcl commands in a single cosimulation block and place `exit` at the end of the command string or Tcl script.

With the exception of the `exit` command, the command string or Tcl script that you specify cannot include commands that load an HDL simulator project or modify simulator state. For example, neither can include commands such as `run`, `stop`, or `reset`.

The following example shows a Tcl script when the `-gui` argument was used with `hdlsimmatlab` or `hdlsimulink`:

```
after 1000 {ncsim -submit exit}
```

This next example is of a Tcl exit script to use when the -tcl argument was used with `hdlsimmatlab` or `hdlsimulink`:

```
after 1000 {exit}
```

To VCD File

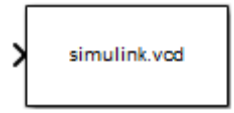
Purpose

Generate value change dump (VCD) file

Library

HDL Verifier

Description



The To VCD File block generates a VCD file that contains information about changes to signals connected to the block's input ports and names the file with the specified file name. You can use VCD files during design verification in the following ways:

- For comparing results of multiple simulation runs, using the same or different simulator environments
- As input to post-simulation analysis tools
- For porting areas of an existing design to a new design

Using the Block Parameters dialog box, you can specify the following parameters:

- The file name to be used for the generated file
- The number of block input ports that are to receive signal data
- The timescale to relate Simulink sample times with HDL simulator ticks

VCD files can grow very large for larger designs or smaller designs with longer simulation runs. However, the only limitation on the size of a VCD file generated by the To VCD File block is the maximum number of signals (and symbols) supported, which is 94^3 (830,584).

You can use the To VCD File block in models running in Normal, Accelerator, or Rapid Accelerator simulation modes. The To VCD File parameters are not tunable in any of the simulation modes. For more

information about these modes, see “How Acceleration Modes Work” in the *Simulink User’s Guide*.

For a description of the VCD file format, see “VCD File Format” on page 1-36.

Note The To VCD File block does not support framed signals.

Note The To VCD File block is integrated into the Simulink Signal & Scope Manager. See the *Simulink User’s Guide* for more information on using the Signal & Scope Manager.

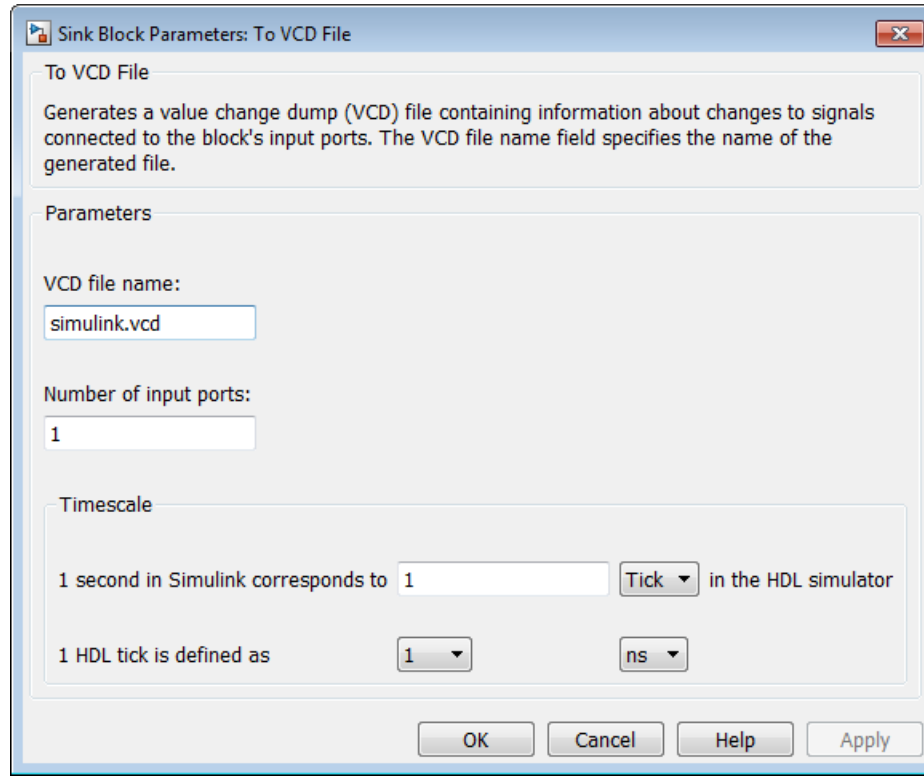
However, when you add a VCD block via the Signal & Scope manager, the signal name that appears in the vcd file may not be the one you specified. After simulation, open the vcd file and check the signal name. You may not see the signal name you specified but instead you may find that In_1 or similar has been used.

If you use the VCD block directly from the HDL Verifier library, the signal names match correctly.

Graphically Displaying VCD File Data

You can graphically display VCD file data or analyze the data with postprocessing tools. For example, the ModelSim `vcd2wlf` tool converts a VCD file to a `WLF` file that you can view in a ModelSim **wave** window. Other examples of postprocessing include the extraction of data pertaining to a particular section of a design hierarchy or data generated during a specific time interval.

Dialog Box



VCD file name

The file name to be used for the generated VCD file. If you specify a file name only, Simulink places the file in your current MATLAB folder. Specify a complete path name to place the generated file in a different location. If you specify the same name for multiple To VCD File blocks, Simulink automatically adds a numeric postfix to identify each instance uniquely.

Note If you want the generated file to have a `.vcd` file type extension, you must specify it explicitly.

Do not give the same file name to different VCD blocks. Doing so results in invalid VCD files.

Number of input ports

The number of block input ports on which signal data is to be collected. The block can handle up to 94^3 (830,584) signals, each of which maps to a unique symbol in the VCD file.

In some cases, a single input port maps to multiple signals (and symbols). This multiple mapping occurs when the input port receives a multidimensional signal.

Because the VCD specification does not include multidimensional signals, Simulink flattens them to a 1D vector in the file.

Timescale

Choose an optimal timing relationship between Simulink and the HDL simulator.

The timescale options specify a correspondence between one second of Simulink time and some quantity of HDL simulator time. You can express this quantity of HDL simulator time in one of the following ways:

- In *relative* terms (i.e., as some number of HDL simulator ticks). In this case, the cosimulation operates in *relative timing mode*, which is the timing mode default.

  To use relative mode, select `Tick` from the pop-up list at the label **in the HDL simulator**, and enter the desired number of ticks in the edit box at **1 second in Simulink corresponds to**. The default value is 1 Tick.

- In *absolute* units (such as milliseconds or nanoseconds). In this case, the cosimulation operates in *absolute timing mode*.

  To use absolute mode, select the desired resolution unit from the pop-up list at the label **in the HDL simulator** (available units are `fs`, `ps`, `ns`, `us`, `ms`, `s`), and enter the desired number of resolution units in the edit box at **1 second in Simulink corresponds to**. Then, set the value of the HDL simulator tick by selecting `1`, `10`, or `100` from the pop-up list at **1 HDL Tick is defined as** and the resolution unit from the pop-up list at **defined as**.

VCD File Format

The format of generated VCD files adheres to IEEE Std 1364-2001. The following table describes the format.

Generated VCD File Format

File Content	Description

`$date`
`23-Sep-2003 14:38:11`
`$end`
	Data and time the file was generated.

`$version HDL Verifier version` `1.0 $ end`	Version of the VCD block that generated the file.
`$timescale 1 ns $ end`	The time scale that was used during the simulation.
`$scope module manchestermodel $end`	The scope of the module being dumped.

Generated VCD File Format (Continued)

File Content	Description

`$var wire 1 ! Original Data [0] $end`
`$var wire 1 " Recovered Clock [0] $end`
`$var wire 1 # Recovered Data [0] $end`
`$var wire 1 $ Data Validity [0] $end`
	Variable definitions. Each definition associates a signal with character identification code (symbol).
	The symbols are derived from printable characters in the ASCII character set from ! to ~.
	Variable definitions also include the variable type (wire) and size in bits.

`$upscope $end`	Marks a change to the next higher level in the HDL design hierarchy.
`$enddefinitions $end`	Marks the end of the header and definitions section.
`#0`	Simulation start time.

`$dumpvars`
`0!`
`0"`
`0#`
`0$`
`$end`
	Lists the values of all defined variables at time equals 0.

Generated VCD File Format (Continued)

File Content	Description
`#630` ` 1!`	The starting point of logged value changes from checks of variable values made at each simulation time increment. This entry indicates that at 63 nanoseconds, the value of signal `Original Data` changed from 0 to 1.

`.`
`.`
`.`
`#1160`
` 1#`
` 1$`
	At 116 nanoseconds the values of signals `Recovered Data` and `Data Validity` changed from 0 to 1.

`$dumpoff`
` x!`
` x"`
` x#`
` x$`
`$end`
	Marks the end of the file by dumping the values of all variables as the value `x`.

2

System Objects — Alphabetical List

hdlverifier.FILSimulation

Purpose

Construct System object for FIL simulation with MATLAB

Description

The FILSimulation System object™ creates, launches, and controls FPGA execution from MATLAB®.

Construction

hdlverifier.FILSimulation is a virtual class and cannot be instantiated directly. To use it, launch the FIL Wizard and generate your own custom FILSimulation derived class. Then you can instantiate your own FIL simulation object with the following function:

`MYFIL=`*`toplevel`*`_fil.m` creates a new instance of the derived class generated by the FIL Wizard from your legacy HDL code.

You can adjust any properties on the System object with write permission by using the get and set methods or by setting the property directly. See "Properties" on page 2-2.

Properties

Connection

Parameters for the connection with the FPGA board

R/W Access: Read only

Default: `char('UDP','192.168.0.2','00-0A-35-02-21-8A')`

Attributes:

Connection type	string, value `UDP`	Example: `'UDP'`
Board IP address	string	Example: `'192.168.0.2'`
Board MAC address (optional)	string	Example: `'00-0A-35-02-21-8A'`

DUTName

DUT top level name

R/W Access: Read only

Default: `''`

Attributes:

Name of DUT top level	string	Example: `'inverter_top'`

FPGABoard

String containing FPGA board name

R/W Access: Read only

Default: `''`

FPGAProgrammingFile

Path to the programming file for the FPGA

R/W Access: Read and write

Default: `''`

Attributes:

Path name	string	Example: `'c:\work\`*`filename`*`'`

FPGAVendor

Name of the FPGA chip vendor

R/W Access: Read only

Default: `'Xilinx'`

Attributes:

Chip vendor name	string	Examples: `'Altera'`, `'Xilinx'`

InputBitWidths

Input widths, in bits

R/W Access: Read only

Default: 0

Attributes:

Integer or vector of integer specifying the bit widths of the inputs. If you provide only a scalar, the inputs each have the same bit width; otherwise you should provide a vector of the same size as the number of inputs.	integer or vector of integers	Examples:
		`10`
		`[12,6]`

InputSignals

Input paths in the HDL code

R/W Access: Read only

Default: `''`

Attributes:

input port name of each input in the HDL	string or array of N string	Examples: `'in1'`, `char('in1','in2')`

OutputBitWidths

Output widths, in bits

R/W Access: Read only

Default: 0

Attributes:

Integer or vector of integer specifying the bit widths of the outputs. If you provide only a scalar, the outputs each have the same bit width. Otherwise you should provide a vector of the same size as the number of outputs.	integer or vector of integers	Examples:
		`10`
		`[12,6]`

OutputDataTypes

Output data types

R/W Access: Read and write

Default: `fixedpoint`

Attributes:

String or array of N string specifying the data type of the output. If you only provide one string, each of the outputs has the same type. Otherwise, you should provide an array of strings of the same size as the number of output.	String or array of strings	Examples: `'logical'`, `'integer'`, `'fixedpoint'` `char(`integer','fixedpoint')`

OutputDownsampling

Downsampling factor and phase of the outputs

R/W Access: Read and write

Default: `[1,0]`

Attributes:

Vector of 2 integers: The first integer specifies the downsampling factor and is positive. The second integer specifies the phase and is null or	vector	Examples: `[3,1]`

positive and inferior to the downsampling factor.

OutputFractionLengths

Output fraction lengths

R/W Access: Read and write

Default: `0`

Attributes:

Integer or vector of integer specifying the fraction length of the outputs. If you provide only a scalar, each output has the same fraction length. Otherwise you should provide a vector of the same size as the number of outputs.	integer or vector of integers	Examples:
		`10`
		`[12,6]`

OutputSignals

Output port name in the HDL top level

R/W Access: Read only

Default: `''`

Attributes:

String or array of N string containing the output port name of each output in HDL.	string or array of strings	Examples: `'out1'`, `char('out1','out2')`

OutputSigned

Sign of the outputs

R/W Access: Read and write

Default: `false`

Attributes:

Boolean or vector of boolean specifying the sign of the outputs. If you provide only a scalar, each output has the same sign. Otherwise, you should provide a vector of the same size as the number of outputs.	Boolean of vector of Boolean	Examples: `true` (signed), `false` (unsigned) `[true, true, false]`

OverclockingFactor

Hardware overclocking factor

R/W Access: Read and write

Default: 1

Attributes:

Positive integer specifying the overclocking factor for the hardware.	integer	Example: 3

ScanChainPosition

Position of the FPGA in the JTAG scan chain

R/W Access: Read only

Default: 1

Attributes:

Positive integer specifying the position of the FPGA in the JTAG scan chain.	integer	Example: 1

SourceFrameSize

Frame size of the source (only for HDL source block)

R/W Access: Read and write

Default: 1

Attributes:

Integer specifying the frame size of the source when the HDL is a source block (no input).	integer	Example: 1

Methods

clone	Create FILSimulation object with same property values
isLocked	System object locked status for input attributes and nontunable properties
programFPGA	Load programming file onto FPGA
release	Release connection to FPGA board and allow changes to object
step	Run FIL simulation for set of inputs and return output

Examples

See FPGA-in-the-Loop simulation using MATLAB System Object .

Purpose

Create FILSimulation object with same property values

Syntax

```
newfilobj = clone(filobj)
```

Description

`newfilobj = clone(filobj)` creates another instance of the System object, `filobj`, with the same property values. The clone method creates a new unlocked object with uninitialized states.

Input Arguments

filobj

Instance of FILSimulation

Output Arguments

newfilobj

New FILSimulation System object with the same property values as the original System object. The new unlocked object contains uninitialized states.

hdlverifier.FILSimulation.isLocked

Purpose

System object locked status for input attributes and nontunable properties

Syntax

```
L = isLocked(filobj)
```

Description

`L = isLocked(filobj)` returns a logical value, `L`, which indicates whether the input attributes and nontunable properties are locked for the FIL simulation System object, `filobj`. The System object performs an internal initialization the first time the `step` method is executed. This initialization locks nontunable properties and input specifications, such as dimensions, complexity, and input data type. After the initialization is complete, `isLocked` method returns a `true` value.

Input Arguments

filobj

Instance of FIL simulation

Output Arguments

L

Logical value. Either `1` (true) or `0` (false).

Purpose

Load programming file onto FPGA

Syntax

```
programFPGA(filobj)
```

Description

`programFPGA(filobj)` loads the FPGA through the JTAG cable using the FILSimulation property information from ProgrammingFile, ScanChainPosition and BoardName.

Input Arguments

filobj

Instance of FILSimulation

hdlverifier.FILSimulation.release

Purpose

Release connection to FPGA board and allow changes to object

Syntax

```
release(filobj)
```

Description

`release(filobj)` releases system resources (such as memory, file handles or hardware connections) of System object, `filobj`. It also allows all its properties and input characteristics to be changed.

Input Arguments

filobj

Instance of FILSimulation

Purpose

Run FIL simulation for set of inputs and return output

Syntax

```
[hdloutputs] = step(filobj,[hdlinputs])
```

Description

`[hdloutputs] = step(filobj,[hdlinputs])` connects to the FPGA, writes `hdlinputs` to the FPGA and reads `hdloutputs` from the FPGA.

Note The object performs an initialization the first time the `step` method is executed. This initialization locks nontunable properties and input specifications, such as dimensions, complexity, and data type of the input data. If you change a nontunable property or an input specification, the System object issues an error. To change nontunable properties or inputs, you must first call the `release` method to unlock the object.

Input Arguments

filobj

Instance of FILSimulation

hdlinputs

Set of inputs to run on FPGA

Output Arguments

hdloutputs

Set of outputs returned by the FPGA

hdlverifier.HDLCosimulation.clone

Purpose

Create HDLCosimulation object with same property values

Syntax

```
newcosimobj = clone(cosimobj)
```

Description

`newcosimobj = clone(cosimobj)` creates another instance of the System object, `cosimobj`, with the same property values. The clone method creates a new unlocked object with uninitialized states.

Input Arguments

cosimobj

Instance of HDLCosimulation

Output Arguments

newcosimobj

New HDL Cosimulation System object with the same property values as the original System object. The new unlocked object contains uninitialized states.

Examples

- Verifying Viterbi Decoder Using MATLAB System Object and Mentor Graphics ModelSim
- Verifying Viterbi Decoder Using MATLAB System Object and Cadence Incisive

See Also

`hdlverifier.HDLCosimulation` | `hdlverifier.HDLCosimulation.display` | `hdlverifier.HDLCosimulation.isLocked` | `hdlverifier.HDLCosimulation.release` | `hdlverifier.HDLCosimulation.reset` | `hdlverifier.HDLCosimulation.set` | `hdlverifier.HDLCosimulation.step` |

Purpose

Display visible properties and their values

Syntax

```
display(cosimobj)
```

Description

`display(cosimobj)` creates another instance of the System object, `cosimobj`, with the same property values. The clone method creates a new unlocked object with uninitialized states.

Input Arguments

cosimobj

Instance of HDLCosimulation

Examples

- Verifying Viterbi Decoder Using MATLAB System Object and Mentor Graphics ModelSim
- Verifying Viterbi Decoder Using MATLAB System Object and Cadence Incisive

See Also

`hdlverifier.HDLCosimulation` | `hdlverifier.HDLCosimulation.clone` | `hdlverifier.HDLCosimulation.isLocked` | `hdlverifier.HDLCosimulation.release` | `hdlverifier.HDLCosimulation.reset` | `hdlverifier.HDLCosimulation.set` | `hdlverifier.HDLCosimulation.step` |

hdlverifier.HDLCosimulation

Purpose

Construct System object for HDL cosimulation with MATLAB

Description

The HDL Cosimulation System object cosimulates MATLAB and a hardware component. It does so by applying input signals to and reading output signals from an HDL model under simulation in the HDL simulator. You can use this object to model a source or sink device by configuring the object with input or output ports only.

Construction

`h = HDLCosimulation(Name,Value)` creates a new instance of HDLCosimulation with additional options specified by one or more `Name,Value` pair arguments. `Name` can also be a property name and `Value` is the corresponding value. `Name` must appear inside single quotes (`' '`). You can specify several name-value pair arguments in any order as `Name1,Value1,...,NameN,ValueN`.

`h = hdlcosim(Name,Value)` creates a new instance of HDLCosimulation using a shortcut constructor.

The Cosimulation Wizard creates an HDL Cosimulation System object using existing HDL code. This workflow creates an HDL launch script for easier startup.

Properties

Connection

Parameters for the connection with the HDL simulator.

- The first element is the connection type (`'SharedMemory'`,`'Socket'`). If shared memory is used, then port number and host name are not applicable.
- The second element is the port number, which must be a positive integer. Optional. It is set to 4449 if not otherwise specified.
- The third element is the host name of the HDL session. Optional. Set to `localhost` if not specified.

Default: {`'SharedMemory'`}

Example values:

```
{'SharedMemory'}
{'Socket'}
{'Socket',1234}
{'Socket',1234,'hostname'}
```

FrameBasedProcessing

Note `FrameBasedProcessing` property will be removed in a future release. Sample mode or frame mode is automatically detected based on the size of the inputs during the step method execution.

Enable frame-based processing

Default: `false`

Example values:

```
true/false
```

InputSignals

Input paths in the HDL code

Default: `''`

Example values:

```
'/top/in1'
{'/top/in1','/top/in2'}
```

OutputFractionLengths

Output fraction lengths. Must be an integer or vector of integer specifying the fraction length of the outputs. If you provide only a scalar, all the outputs are of the same type. Otherwise, provide a vector of the same size as the number of outputs.

Default: `0`

Example values:

```
10
[12,6]
```

OutputSignals

Output paths in the HDL code

Default: `''`

Example values:

```
'/top/out1'
{'/top/out1','/top/out2'}
```

OutputSigned

Output sign. Must be a boolean or vector of boolean specifying the sign of the outputs. If you provide only a scalar, all outputs are of the same type. Otherwise, provide a vector of the same size as the number of outputs.

Default: `false`

Example values:

```
true/false
[true,true]
```

PreRunTime

Delay in HDL simulator before the cosimulation starts

Default: {`0,'ns'`}

Example values:

```
{10,'fs'}
{25,'ps'}
{4,'ns'}
```

```
{500,'us'}
{5,'ms'}
{1,'s'}
```

SampleTime

Elapsed time in the HDL simulator between each call to step

Default: {10,'ns'}

Example values:

```
{10,'fs'}
{25,'ps'}
{4,'ns'}
{500,'us'}
{5,'ms'}
{1,'s'}
```

TclPostSimulationCommand

Tcl post-simulation command executed by the HDL simulator during a call to release

Default: ''

Example value:

```
'echo "done"'
```

TclPreSimulationCommand

Tcl presimulation command executed by the HDL simulator during the first call to step or during the next call to step after a call to release

Default: ''

Example value:

```
'force /top/rst 1 0, 0 2 ns; force /top/clk 0 0, 1 1 ns -repeat 2 ns'
```

Methods

clone	Create HDLCosimulation object with same property values
display	Display visible properties and their values
isLocked	System object locked status for input attributes and nontunable properties
release	Release connection to HDL simulator and allow changes to object
reset	Unlock object, release connection to HDL simulator, and reset internal state
set	Change System object property value
step	Run HDL simulator for set of inputs and return output

Examples

- Verifying Viterbi Decoder Using MATLAB System Object and Mentor Graphics ModelSim
- Verifying Viterbi Decoder Using MATLAB System Object and Cadence Incisive

Purpose

System object locked status for input attributes and nontunable properties

Syntax

```
L = isLocked(cosimobj)
```

Description

`L = isLocked(cosimobj)` returns a logical value, `L`, which indicates whether the input attributes and nontunable properties are locked for the HDL Cosimulation System object, `cosimobj`. The System object performs an internal initialization the first time the `step` method is executed. This initialization locks nontunable properties and input specifications, such as dimensions, complexity, and input data type. After the initialization is complete, `isLocked` method returns a `true` value.

Input Arguments

`cosimobj`

Instance of HDLCosimulation

Output Arguments

`L`

Logical value. Either `1` (true) or `0` (false).

Examples

- Verifying Viterbi Decoder Using MATLAB System Object and Mentor Graphics ModelSim
- Verifying Viterbi Decoder Using MATLAB System Object and Cadence Incisive

See Also

`hdlverifier.HDLCosimulation` | `hdlverifier.HDLCosimulation.clone` | `hdlverifier.HDLCosimulation.display` | `hdlverifier.HDLCosimulation.release` | `hdlverifier.HDLCosimulation.reset` | `hdlverifier.HDLCosimulation.set` | `hdlverifier.HDLCosimulation.step` |

hdlverifier.HDLCosimulation.release

Purpose

Release connection to HDL simulator and allow changes to object

Syntax

```
release(cosimobj)
```

Description

`release(cosimobj)` releases system resources (such as memory, file handles or hardware connections) of System object, `cosimobj`. It also allows all its properties and input characteristics to be changed.

Input Arguments

cosimobj

Instance of HDLCosimulation

Examples

- Verifying Viterbi Decoder Using MATLAB System Object and Mentor Graphics ModelSim
- Verifying Viterbi Decoder Using MATLAB System Object and Cadence Incisive

See Also

`hdlverifier.HDLCosimulation` | `hdlverifier.HDLCosimulation.clone` | `hdlverifier.HDLCosimulation.display` | `hdlverifier.HDLCosimulation.isLocked` | `hdlverifier.HDLCosimulation.reset` | `hdlverifier.HDLCosimulation.set` | `hdlverifier.HDLCosimulation.step` |

Purpose

Unlock object, release connection to HDL simulator, and reset internal state

Syntax

```
reset(cosimobj)
```

Description

`reset(cosimobj)` unlocks the System object, `cosimobj`, and releases its connection with the HDL simulator. It also resets all internal states.

Input Arguments

cosimobj

Instance of HDLCosimulation

Examples

- Verifying Viterbi Decoder Using MATLAB System Object and Mentor Graphics ModelSim
- Verifying Viterbi Decoder Using MATLAB System Object and Cadence Incisive

See Also

`hdlverifier.HDLCosimulation` | `hdlverifier.HDLCosimulation.clone` | `hdlverifier.HDLCosimulation.display` | `hdlverifier.HDLCosimulation.isLocked` | `hdlverifier.HDLCosimulation.release` | `hdlverifier.HDLCosimulation.reset` | `hdlverifier.HDLCosimulation.set` | `hdlverifier.HDLCosimulation.step` |

hdlverifier.HDLCosimulation.set

Purpose

Change System object property value

Syntax

```
set(cosimobj,'PropertyName',PropertyValue)
```

Description

`set(cosimobj,'PropertyName',PropertyValue)` sets the specified `Property` of System object, `cosimobj`, with the specified value, after validating the new value.

Input Arguments

cosimobj

Instance of HDLCosimulation

PropertyName

Object property name. See “Properties” on page 2-18 for hdlverifier.HDLCosimulation.

PropertyValue

Object property value for `PropertyName`. See “Properties” on page 2-18 for hdlverifier.HDLCosimulation.

Examples

- Verifying Viterbi Decoder Using MATLAB System Object and Mentor Graphics ModelSim
- Verifying Viterbi Decoder Using MATLAB System Object and Cadence Incisive

See Also

`hdlverifier.HDLCosimulation` | `hdlverifier.HDLCosimulation.clone` | `hdlverifier.HDLCosimulation.display` | `hdlverifier.HDLCosimulation.isLocked` | `hdlverifier.HDLCosimulation.release` | `hdlverifier.HDLCosimulation.reset` | `hdlverifier.HDLCosimulation.step` |

Purpose

Run HDL simulator for set of inputs and return output

Syntax

```
[hdloutputs] = step(cosimobj,hdlinputs)
```

Description

`[hdloutputs] = step(cosimobj,hdlinputs)` connects to the HDL simulator, writes `hdlinputs` to the HDL simulator and reads `hdloutputs` from the HDL simulator. The elapsed HDL simulator time between each call to step is defined by the SampleTime property.

Note The object performs an initialization the first time the `step` method is executed. This initialization locks nontunable properties and input specifications, such as dimensions, complexity, and data type of the input data. If you change a nontunable property or an input specification, the System object issues an error. To change nontunable properties or inputs, you must first call the `release` method to unlock the object.

Input Arguments

cosimobj

Instance of HDLCosimulation

hdlinputs

Set of inputs for HDL simulator to run

Output Arguments

hdloutputs

Set of outputs returned by HDL simulator

Examples

- Verifying Viterbi Decoder Using MATLAB System Object and Mentor Graphics ModelSim
- Verifying Viterbi Decoder Using MATLAB System Object and Cadence Incisive

See Also

hdlverifier.HDLCosimulation | hdlverifier.HDLCosimulation.clone | hdlverifier.HDLCosimulation.display | hdlverifier.HDLCosimulation.isLocked | hdlverifier.HDLCosimulation.release | hdlverifier.HDLCosimulation.reset | hdlverifier.HDLCosimulation.set |

3

Functions — Alphabetical List

breakHdlSim

Purpose

Execute `stop` command in HDL simulator from MATLAB

Syntax

```
breakHdlSim()
breakHdlSim('portNumber')
breakHdlSim('portNumber','hostName')
```

Description

`breakHdlSim()` executes a stop command on the HDL simulator on the local host. Use this function to unblock the HDL simulator after the HDL simulator has loaded the simulation but before Simulink starts the simulation. If, after starting the simulation, you decide to add more signals to the waveform window, use this function to unblock the HDL simulator first. When you use`breakHdlSim`, make sure that you specify the current connection information to the HDL simulator.

`breakHdlSim('portNumber')` executes a stop command on the HDL simulator on port *portNumber*.

`breakHdlSim('portNumber','hostName')` executes a stop command on the HDL simulator on host *hostName*.

Examples

Stop the HDL simulator that is currently running on the local host.

```
>> breakHdlSim()
```

Stop the HDL simulator that is currently running on port 1234.

```
>> breakHdlSim('1234')
```

Stop the HDL simulator that is currently running on port 1234 and host "mylinux".

```
>> breakHdlSim('1234', 'mylinux')
```

See Also

`pingHdlSim`

Purpose

Run HDL Cosimulation Wizard

Syntax

```
cosimWizard
```

Description

`cosimWizard` invokes the HDL Cosimulation Wizard. You provide the HDL code and related input data for creating a MATLAB function, MATLAB System object, or Simulink block for cosimulation with the HDL simulator. The supported HDL simulators include ModelSim and Questa® from Mentor Graphics® and Cadence Incisive®.

- For cosimulation between Simulink and the HDL simulator: The Cosimulation Wizard generates an HDL cosimulation block for use in a Simulink model, and MATLAB scripts that compile an HDL design and launch the HDL simulator.
- For cosimulation between MATLAB and the HDL simulator using MATLAB System objects: The Cosimulation Wizard generates a cosimulation System object customized to your design that compiles the HDL code and launches the HDL simulator.
- For cosimulation between MATLAB and the HDL simulator with MATLAB callback functions: The Cosimulation Wizard generates templates for MATLAB component or testbench callback functions and MATLAB scripts that compile the HDL design and launch the HDL simulator.

Examples

Invoke HDL Cosimulation Wizard:

```
>>cosimWizard
```

The Cosimulation Wizard starts.

Tutorials

- “HDL Cosimulation Wizard Tutorials”

How To

- “Import HDL Code With the HDL Cosimulation Wizard”

dec2mvl

Purpose

Convert decimal integer to binary string

Syntax

```
dec2mvl(d)
dec2mvl(d,n)
```

Description

`dec2mvl(d)` returns the binary representation of `d` as a multivalued logic string. `d` must be an integer smaller than 2^52.

`dec2mvl(d,n)` produces a binary representation with at least `n` bits.

Examples

The following function call returns the string '10111':

```
>>dec2mvl(23)
```

The following function call returns the string '01001':

```
>>dec2mvl(-23)
```

The following function call returns the string '11101001':

```
>>dec2mvl(-23,8)
```

See Also

`mvl2dec`

Purpose

Run FPGA-in-the-Loop Wizard

Syntax

```
filWizard
filWizard(FILENAME)
```

Description

`filWizard` invokes the FPGA-in-the-Loop (FIL) Wizard. You provide the HDL code and all related information for creating a FIL block for simulation with an FPGA device.

`filWizard(FILENAME)` relaunches the FIL Wizard using information saved in the specified FILENAME MAT-file. At the end of each FIL Wizard session, a MAT-file that contains the session information is saved to disk. This MAT-file can be used to restore the session later.

Examples

Invoke FPGA-in-the-Loop Wizard:

```
>> filWizard
```

The FPGA-in-the-Loop Wizard starts.

How To

- "FIL Interface Generation with the FIL Wizard"
- "Performing FPGA-in-the-Loop Simulation"

hdldaemon

Purpose

Control MATLAB server that supports interactions with HDL simulator

Syntax

```
hdldaemon
hdldaemon(Name, Value)
hdldaemon(Option)

s=hdldaemon( ___ )
```

Description

`hdldaemon` starts the HDL Link MATLAB server using shared memory inter-process communication. Only one `hdldaemon` per MATLAB session can be running at any given time.

`hdldaemon(Name, Value)` uses additional options specified by one or more `Name, Value` pair arguments.

- If you do not specify memory type, the server starts using shared memory.
- If you specify the `socket` `Name, Value` argument, the server starts using socket memory..

Note If server is already running, issuing `hdldaemon` with these arguments shuts down the current server and then starts a new server session using shared memory (unless socket is specified).

`hdldaemon(Option)` accepts a single optional input. Only one option may be specified in a single call. You must establish the server connection before calling `hdldaemon` with one of these options.

`s=hdldaemon( ___ )` returns the server status connection in structure `s`, using any of the input arguments in the previous syntaxes.

Input Arguments

Option - Server option to shut down MATLAB server or display server status

`'kill' | 'stop' | 'status'`

Server option to shut down MATLAB server or display server status, specified as one of these strings:

`'kill'`	Shuts down the MATLAB server without shutting down MATLAB.
`'stop'`	Shuts down the MATLAB server without shutting down MATLAB. There is no difference between using `'kill'` and `'stop'`.
`'status'`	Displays status of the MATLAB server. You can also use `s=hdldaemon('status')`, which displays MATLAB server status and returns status in structure `s`.

Name-Value Pair Arguments

Specify optional comma-separated pairs of `Name,Value` arguments. `Name` is the argument name and `Value` is the corresponding value. `Name` must appear inside single quotes (`' '`). You can specify several name and value pair arguments in any order as `Name1,Value1,...,NameN,ValueN`.

Example: `'time','int64','quiet','true'` specifies time values are returned as 64-bit integers and output messages are suppressed.

'time' - Instruction to MATLAB server on how it should send and return time values

`'sec'` (default) | `'int64'`

Instruction to MATLAB server on how it should send and return time values, specified as the comma-separated pair consisting of `'time'` and one of these values:

`'int64'`	Specifies that the MATLAB server send and return time values in the MATLAB function callbacks as 64-bit integers representing the number of simulation steps.MATLAB See the `matlabcp/matlabtb` tnow parameter reference ("MATLAB Function Syntax and Function Argument Definitions").
`'sec'`	Specifies that the MATLAB server sends and returns time values in the MATLAB function callbacks as `double` values that HDL Verifier scales to seconds based on the current HDL simulation resolution.

If server is already running, issuing `hdldaemon` with the `time` parameter alone will shut down the current server and start the server up again using shared memory.

Example: `'time','int64'`

'quiet' - Indicator to suppress printing diagnostic messages

`'false'` (default) | `'true'`

Indicator to suppress printing diagnostic messages, specified as the comma-separated pair consisting of `'quiet'` and one of the following values:

`'true'`	Suppress printing diagnostic messages.
`'false'`	Do not suppress printing diagnostic messages.

Errors still appear. Use this option to suppress the MATLAB server shutdown message when using `hdldaemon` to get an unused socket number. If server is already running, issuing `hdldaemon` with the `quiet` parameter alone will shut down the current server and start the server up again using shared memory.

Example: `'quiet', 'true'`

'socket' - TCP/IP port used for communication

'0' | string

TCP/IP port used for communication, specified as the comma-separated pair consisting of 'socket' and a string. The string can be either '0', indicating that the host automatically chooses a valid TCP/IP port, or an explicit port number (1024 < port < 49151) or a service (alias) name from /etc/services file.

If you specify the operating system option (0), use hdldaemon('status') to acquire the assigned socket port number.

Example: 'socket','4449'

'tclcmd' - Tcl command transmitted to all connected clients

string

Tcl command transmitted to all connected clients, specified as any valid Tcl command string.

The Tcl command string you specify cannot include commands that load an HDL simulator project or modify simulator state. For example, the string cannot include commands such as start, stop, or restart (for ModelSim) or run, stop, or reset (for Incisive).

Note You can issue this command only after the software establishes a server connection.

Caution

Do not call hdldaemon('tclcmd', 'Tcl command string') from inside a matlabtb or matlabcp function. Doing so results in a race condition, and the simulator hangs.

Example: 'tclcmd','puts' '"done"'

Output Arguments

s - Structure containing information about the connection

`'comm' | 'connections' | 'ipc_id'`

Structure containing information about the connection. The structure contains the following variables:

`'comm'`	Either `'shared memory'` or `'sockets'`
`'connections'`	Number of open connections
`'ipc_id'`	If shared memory, file system name for the shared memory communication channel. If socket, the TCP/IP port number.

Examples

Start MATLAB Server With Shared Memory

Start the MATLAB server using shared memory communication and use an integer representation of time.

```
hdldaemon('time', 'int64')
```

Start MATLAB Server With Socket Communication

Start MATLAB server and specify socket communication on port 4449.

```
hdldaemon('socket', '4449')
```

Check Server Status

```
hdldaemon('status')
```

The following are some examples of the messages you might see, depending on your server connection:

- With one or more connections:

```
HDLDaemon socket server is running on port 4449 with 1 connections
```

- With no connections:

```
HDLDaemon shared memory server is running with 0 connections
```

- Server has not been started:

```
HDLDaemon is NOT running
```

Check Connection Information

Check connection information for communication mode, number of existing connections, and the interprocess communication identifier (`ipc_id`) the MATLAB server is using for a link.

```
x=hdldaemon('status')
```

The following is an example of the returned message for a socket connection:

```
x =
           comm: 'sockets'
    connections: 0
         ipc_id: '4449'
```

The following is an example of the returned message for a shared memory connection:

```
x =
           comm: 'shared memory'
    connections: 0
         ipc_id:  '\\.\pipe\E505F434-F023-42a6-B06D-DEFD08434C67'
```

You can examine `ipc_id` by entering it at the MATLAB command prompt:

```
x.ipc_id
```

```
 '\\.\pipe\E505F434-F023-42a6-B06D-DEFD08434C67'
```

Shut Down Server

Shut down server without shutting down MATLAB.

```
hdldaemon('kill')
```

Issue Tcl Commands

Issue simple or complex Tcl commands.

Simple example:

```
hdldaemon('tclcmd','puts "This is a test"')
```

Complex example:

```
tclcmd = {  ['cd ',unixprojdir],...
            'vlib work',... %create library (if applicable)
           ['vcom -performdefaultbinding ' unixsrcfile1],...
           ['vcom -performdefaultbinding ' unixsrcfile2],...
           ['vcom -performdefaultbinding ' unixsrcfile3],...
            'vsimmatlab work.osc_top ',...
            'matlabcp u_osc_filter -mfunc oscfilter',...
            'add wave sim:/osc_top/clk',...
            'add wave sim:/osc_top/clk_enable',...
            'add wave sim:/osc_top/reset',...
           ['add wave -height 100 -radix decimal -format analog-step...
       -scale 0.001 -offset 50000 ', 'sim:/osc_top/osc_out'],...
           ['add wave -height 100 -radix decimal -format analog-step...
       -scale 0.00003125 -offset 50000 ', 'sim:/osc_top/filter1x_out'],...
           ['add wave -height 100 -radix decimal -format analog-step...
       -scale 0.00003125 -offset 50000 ', 'sim:/osc_top/filter4x_out'],...
           ['add wave -height 100 -radix decimal -format analog-step...
       -scale 0.00003125 -offset 50000 ', 'sim:/osc_top/filter8x_out'],...
            'force sim:/osc_top/clk_enable 1 0',...
            'force sim:/osc_top/reset 1 0, 0 120 ns',...
```

```
'force sim:/osc_top/clk 1 0 ns, 0 40 ns -r 80ns',...
};
```

This example is taken from "Implementing the Filter Component of an Oscillator in MATLAB". See the full example for use of this complex Tcl command in context.

See Also

`nclaunch | vsim`

Related Examples

- Implementing the Filter Component of an Ocsillator in MATLAB

Concepts

- “Starting the HDL Simulator from MATLAB”

hdlsimmatlab

Purpose

Load instantiated HDL design for verification with Cadence Incisive and MATLAB

Syntax

```
hdlsimmatlab <instance> [<ncsim_args>]
```

Description

The `hdlsimmatlab` command loads the specified instance of an HDL design for verification and sets up the Cadence Incisive simulator so it can establish a communication link with MATLAB. The Cadence Incisive simulator opens a simulation workspace as it loads the HDL design.

This command may be run from the HDL simulator prompt or from a Tcl script shell (`tclsh`).

This command is issued in the HDL simulator.

Arguments

`<instance>`
: Specifies the instance of an HDL design to load for verification.

`<ncsim_args>`
: Specifies one or more `ncsim` command arguments. For details, see the description of `ncsim` in the Cadence Incisive simulator documentation.

Examples

The following command loads the module instance `parse` from library `work` for verification and sets up the Cadence Incisive simulator so it can establish a communication link with MATLAB:

```
tclshell> hdlsimmatlab work.parse
```

Purpose

Load instantiated HDL design for cosimulation with Cadence Incisive and Simulink

Syntax

```
hdlsimulink <instance> [<ncsim_args>]
```

Description

The `hdlsimulink` command loads the specified instance of an HDL design for cosimulation and sets up the Cadence Incisive simulator so it can establish a communication link with Simulink. The Cadence Incisive simulator opens a simulation workspace into which it loads the HDL design.

This command is issued in the HDL simulator. The communication mode is determined by the call to `nclaunch`, which must be issued before you call `hdlsimulink`.

Argument

`<instance>`
: Specifies the instance of an HDL design to load for cosimulation.

`<ncsim_args>`
: Specifies one or more `ncsim` command arguments. Do not use `-GUI`, `-BATCH`, or `-TCL`. For more information on `ncsim` arguments, see the description of `ncsim` in the Cadence Incisive simulator documentation.

Examples

The following command loads the module instance `parse` from library `work` for cosimulation, sets up the Cadence Incisive simulator so it can establish a communication link with Simulink, and opens a Tcl script shell:

```
tclshell> hdlsimulink -gui work.parse
```

matlabcp

Purpose

Associate MATLAB component function with instantiated HDL design

Syntax

```
matlabcp <instance>
[<time-specs>]
[-socket <tcp-spec>]
[-rising <port>[,<port>...]]
[-falling <port> [,<port>,...]]
[-sensitivity <port>[,<port>,...]]
[-mfunc <name>]
[-use_instance_obj]
[-argument]
```

Description

The `matlabcp` command has the following characteristics:

- Starts the HDL simulator client component of the HDL Verifier software.
- Associates a specified instance of an HDL design created in the HDL simulator with a MATLAB function.
- Creates a process that schedules invocations of the specified MATLAB function.
- Cancels any pending events scheduled by a previous `matlabcp` command that specified the same instance. For example, if you issue the command `matlabcp` for instance `foo`, all previously scheduled events initiated by `matlabcp` on `foo` are canceled.

This command is issued in the HDL simulator.

MATLAB component functions simulate the behavior of modules in the HDL model. A stub module (providing port definitions only) in the HDL model passes its input signals to the MATLAB component function. The MATLAB component processes this data and returns the results to the outputs of the stub module. A MATLAB component typically provides some functionality (such as a filter) that is not yet implemented in the HDL code. See “Using a MATLAB Function as a Component”.

Notes The communication mode that you specify for `matlabcp` must match the communication mode you specified for `hdldaemon` when you established the server connection.

For socket communications, specify the port number you selected for `hdldaemon` when you issue a link request with the `matlabcp` command in the HDL simulator.

Arguments

`<instance>`

Specifies an instance of an HDL design that is associated with a MATLAB function. By default, `matlabcp` associates the instance to a MATLAB function that has the same name as the instance. For example, if the instance is `myfirfilter`, `matlabcp` associates the instance with the MATLAB function `myfirfilter` (note that hierarchy names are ignored; for example, if your instance name is `top.myfirfilter`, `matlabcp` would associate only `myfirfilter` with the MATLAB function). Alternatively, you can specify a different MATLAB function with `-mfunc`.

Note Do not specify an instance of an HDL module that has already been associated with a MATLAB function (via `matlabcp` or `matlabtb`). If you do, the new association overwrites the existing one.

`<time-specs>`

Specifies a combination of time specifications consisting of any or all of the following:

`<timen>,...`

Specifies one or more discrete time values at which the HDL simulator calls the specified MATLAB function. Each time value is relative to the current simulation time. Even if you do not specify a time, the HDL simulator calls the MATLAB function once at the start of the simulation. Separate multiple time values by a space.For example:

```
matlabtb vlogtestbench_top 10 ns, 10 ms, 10 sec
```

The MATLAB function executes when time equals 0 and then 10 nanoseconds, 10 milliseconds, and 10 seconds from time zero.

Note For time-based parameters, you can specify any standard time units (`ns`, `us`, and so on). If you do not specify units, the command treats the time value as a value of HDL simulation ticks.

`-repeat <time>`

Specifies that the HDL simulator calls the MATLAB function repeatedly based on the specified `<timen>,...` pattern. The time values are relative to the value of `tnow` at the time the HDL simulator first calls the MATLAB function.

`-cancel <time>`

Specifies a time at which the specified MATLAB function stops executing. The time value is relative to the value of `tnow` at the time the HDL simulator first calls the MATLAB function. If you do not specify a cancel time, the application calls the MATLAB function until you finish the simulation, quit the session, or issue a `nomatlabtb` call.

Note The -cancel option works only with the <time-specs> arguments. It does not affect any of the other scheduling arguments for `matlabcp`.

Note Place time specifications after the `matlabcp` instance and before any additional command arguments; otherwise the time specifications are ignored.

All time specifications for the matlabcp functions appear as a number and, optionally, a time unit:

- fs (femtoseconds)
- ps (picoseconds)
- ns (nanoseconds)
- us (microseconds)
- ms (milliseconds)
- sec (seconds)
- no units (tick)

`-socket <tcp_spec>`

Specifies that HDL Verifier use TCP/IP sockets to communicate between the HDL simulator and MATLAB. Shared memory is the default mode of communication and takes effect if you do not specify -socket <tcp_spec> on the command line. The communication mode that you specify with the `matlabcp` command must match the communication mode that you issued with the hdldaemon command.

`-rising <signal>[, <signal>...]`

Indicates that the application calls the specified MATLAB function on the rising edge (transition from `'0'` to `'1'`) of any of the specified signals. Specify -rising with the path names of one or more signals defined as a logic type (`STD_LOGIC`, `BIT`, `XO1`, and so on).

For determining signal transition in:

- VHDL: Rising edge is {0 or L} to {1 or H}.

- Verilog: Rising edge is the transition from 0 to x, z, or 1, and from x or z to 1.

Note When specifying signals with the -rising, -falling, and -sensitivity options, specify them in full path name format. If you do not specify a full path name, the command applies the HDL simulator rules to resolve signal specifications.

`-falling <signal>[, <signal>...]`

Indicates that the application calls the specified MATLAB function whenever any of the specified signals experiences a falling edge—changes from `'1'` to `'0'`. Specify -falling with the path names of one or more signals defined as a logic type (`STD_LOGIC`, `BIT`, `XO1`, and so on).

For determining signal transition in:

- VHDL: Falling edge is {1 or H} to {0 or L}.
- Verilog: Falling edge is the transition from 1 to x, z, or 0, and from x or z to 0.

Note When specifying signals with the -rising, -falling, and -sensitivity options, specify them in full path name format. If you do not specify a full path name, the command applies the HDL simulator rules to resolve signal specifications.

`-sensitivity <signal>[, <signal>...]`

Indicates that the application calls the specified MATLAB function whenever any of the specified signals changes state. Specify -sensitivity with the path names of one or more signals. Signals of any type can appear in the sensitivity list and can be positioned at any level in the HDL model hierarchy.

Note When specifying signals with the -rising, -falling, and -sensitivity options, specify them in full path name format. If you do not specify a full path name, the command applies the HDL simulator rules to resolve signal specifications.

`-mfunc <name>`
: The name of the MATLAB function that is associated with the HDL module instance you specify for `instance`. By default, the HDL Verifier software invokes a MATLAB function that has the same name as the specified HDL instance. Thus, if the names are the same, you can omit the -mfunc option. If the names are not the same, use this argument when you call `matlabcp`. If you omit this argument and `matlabcp` does not find a MATLAB function with the same name, the command generates an error message.

`-use_instance_obj`
: Instructs the function specified with the argument -mfunc to use an HDL instance object passed by HDL Verifier to the function. This argument has the fields shown in the following table. See "Writing Functions Using the HDL Instance Object" for examples.

Field	Read/Write Access	Description
`tnext`	Write only	Used to schedule a callback during the set time value. This field is equivalent to old tnext. For example: `hdl_instance_obj.tnext = hdl_instance_obj.tnow + 5e-9` will schedule a callback at time equals 5 nanoseconds from tnow.
`userdata`	Read/Write	Stores state variables of the current `matlabcp` instance. You can retrieve the variables the next time the callback of this instance is scheduled.

Field	Read/Write Access	Description

simstatus	Read only	Stores the status of the HDL simulator. The HDL Verifier software sets this field to 'Init' during the first callback for this particular instance and to 'Running' thereafter. simstatus is a read-only property.
		
		`>> hdl_instance_obj.simstatus`
		
		`ans=`
		`Init`

instance	Read only	Stores the full path of the Verilog/VHDL instance associated with the callback. instance is a read-only property. The value of this field equals that of the module instance specified with the function call. For example:
		
		In the HDL simulator:
		
		`hdlsim> matlabcp osc_top -mfunc oscfilter use_instance_obj`
		
		In MATLAB:
		
		`>> hdl_instance_obj.instance`
		
		`ans=`
		`osc_top`

Field	Read/Write Access	Description

`argument`	Read only	Stores the argument set by the -argument option of `matlabcp`. For example:
		
		`matlabtb osc_top -mfunc oscfilter -use_instance_obj -argument foo`
		
		The link software supports the -argument option only when it is used with -use_instance_obj, otherwise the argument is ignored. argument is a read-only property.
		
		`>> hdl_instance_obj.argument`
		
		`ans=`
		`foo`

`portinfo`	Read only	Stores information about the VHDL and Verilog ports associated with this instance. portinfo is a read-only property, which has a field structure that describes the ports defined for the associated HDL module. For each port, the portinfo structure passes information such as the port's type, direction, and size. For more information on port data, see "Gaining Access to and Applying Port Information". `hdl_instance_obj.portinfo.`*`field1.field2.field3`* **Note** When you use use_instance_obj, you access tscale through the HDL instance object. If you do not use use_instance_obj, you can still access tscale through portinfo.

Field	Read/Write Access	Description

tscale	Read only	Stores the resolution limit (tick) in seconds of the HDL simulator. tscale is a read-only property.
		
		`>> hdl_instance_obj.tscale`
		
		`ans=`
		`1.0000e-009`
		
		Note When you use use_instance_obj, you access tscale through the HDL instance object. If you do not use use_instance_obj, you can still access tscale through portinfo.

tnow	Read only	Stores the current time. tnow is a read-only property. `hdl_instance_obj.tnext = hld_instance_obj.tnow + fastestrate;`

portvalues	Read/Write	Stores the current values of and sets new values for the output and input ports for a matlabcp instance. For example:
		
		`>> hdl_instance_obj.portvalues`
		
		`ans =`
		`Read Only Input ports:`
		`clk_enable: []`
		`clk: []`
		`reset: []`
		`Read/Write Output ports:`
		`sine_out: [22x1 char]`

linkmode	Read only	Stores the status of the callback. The HDL Verifier software sets this field to 'testbench' if the callback is

Field	Read/Write Access	Description

		associated with `matlabtb` and 'component' if the callback is associated with `matlabcp`. linkmode is a read-only property.
		
		`>> hdl_instance_obj.linkmode`
		
		`ans=`
		` component`

`-argument`
: Used to pass user-defined arguments from the `matlabcp` invocation on the HDL side to the MATLAB function callbacks. Supported with -use_instance_obj only. See the field listing under the -use_instance_obj property.

Examples

The following examples demonstrate some ways you might use the `matlabcp` function.

Using matlabcp with the -mfunc option to Associate an HDL Component with a MATLAB Function of a Different Name

This example explicitly associates the Verilog module vlogtestbench_top.u_matlab_component with the MATLAB function `vlogmatlabc` using the `-mfunc` option. The `'-socket'` option specifies using socket communication on port 4449.

```
hdlsim>matlabcp vlogtestbench_top.u_matlab_component -mfunc vlogmatlabc -socket 4449
```

Using matlabcp with Explicit Times and the -cancel Option

This example includes explicit times with the -cancel option.

```
hdlsim>matlabcp vlogtestbench_top 1e6 fs  3 2e3 ps -repeat 3 ns -cancel 7ns
```

Using matlabcp with Rising and Falling Edges

This example implicitly associates the Verilog module, vlogtestbench_top, with the MATLAB function vlogtestbench_top, and also uses rising and falling edges.

```
hldsim> matlabcp vlogtestbench_top  1 2 3 4 5 6 7 -rising outclk3
          -falling u_matlab_component/inoutclk
```

Purpose

Schedule MATLAB test bench session for instantiated HDL module

Syntax

```
matlabtb <instance>
[<time-specs>]
[-socket <tcp-spec>]
[-rising <port>[,<port>...]]
[-falling <port> [,<port>,...]]
[-sensitivity <port>[,<port>,...]]
[-mfunc <name>]
[-use_instance_obj]
[-argument]
```

Description

The `matlabtb` command has the following characteristics:

- Starts the HDL simulator client component of the HDL Verifier software.
- Associates a specified instance of an HDL design created in the HDL simulator with a MATLAB function.
- Creates a process that schedules invocations of the specified MATLAB function.
- Cancels any pending events scheduled by a previous `matlabtb` command that specified the same instance. For example, if you issue the command `matlabtb` for instance `foo`, all previously scheduled events initiated by `matlabtb` on `foo` are canceled.

This command is issued in the HDL simulator.

MATLAB test bench functions mimic stimuli passed to entities in the HDL model. You force stimulus from MATLAB or HDL scheduled with `matlabtb`.

Notes The communication mode that you specify for `matlabtb` must match the communication mode you specified for `hdldaemon` when you established the server connection.

For socket communications, specify the port number you selected for `hdldaemon` when you issue a link request with the `matlabtb` command in the HDL simulator.

Arguments

`<instance>`

Specifies the instance of an HDL module that the HDL Verifier software associates with a MATLAB test bench function. By default, `matlabtb` associates the instance with a MATLAB function that has the same name as the instance. For example, if the instance is `myfirfilter`, `matlabtb` associates the instance with the MATLAB function `myfirfilter` (note that hierarchy names are ignored; for example, if your instance name is `top.myfirfilter`, `matlabtb` would associate only `myfirfilter` with the MATLAB function). Alternatively, you can specify a different MATLAB function with `-mfunc`.

Note Do not specify an instance of an HDL module that has already been associated with a MATLAB function (via `matlabcp` or `matlabtb`). If you do, the new association overwrites the existing one.

`<time-specs>`

Specifies a combination of time specifications consisting of any or all of the following:

`<timen>,...`

Specifies one or more discrete time values at which the HDL simulator calls the specified MATLAB function. Each time value is relative to the current simulation time. Even if you do not specify a time, the HDL simulator calls the MATLAB function once at the start of the simulation. Separate multiple time values by a space.For example:

```
matlabtb vlogtestbench_top 10 ns, 10 ms, 10 sec
```

The MATLAB function executes when time equals 0 and then 10 nanoseconds, 10 milliseconds, and 10 seconds from time zero.

Note For time-based parameters, you can specify any standard time units (`ns`, `us`, and so on). If you do not specify units, the command treats the time value as a value of HDL simulation ticks.

`-repeat <time>`

Specifies that the HDL simulator calls the MATLAB function repeatedly based on the specified `<timen>,...` pattern. The time values are relative to the value of `tnow` at the time the HDL simulator first calls the MATLAB function.For example:

```
matlabtb vlogtestbench_top 5 ns -repeat 10 ns
```

The MATLAB function executes at time equals 0 ns, 5 ns, 15 ns, 25 ns, and so on.

`-cancel <time>`

Specifies a time at which the specified MATLAB function stops executing. The time value is relative to the value of `tnow` at the time the HDL simulator first calls the MATLAB function. If you do not specify a cancel time, the application calls the MATLAB function until you finish the simulation, quit the session, or issue a `nomatlabtb` call.

Note The -cancel option works only with the <time-specs> arguments. It does not affect any of the other scheduling arguments for `matlabtb`.

Note Place time specifications after the `matlabtb` instance and before any additional command arguments; otherwise the time specifications are ignored.

All time specifications for the matlabtb functions appear as a number and, optionally, a time unit:

- fs (femtoseconds)
- ps (picoseconds)
- ns (nanoseconds)
- us (microseconds)
- ms (milliseconds)
- sec (seconds)
- no units (tick)

`-socket <tcp_spec>`

Specifies TCP/IP socket communication for the link between the HDL simulator and MATLAB. When you provide TCP/IP information for `matlabtb`, you can choose a TCP/IP port number or TCP/IP port alias or service name for the `<tcp_spec>` parameter. If you are setting up communication between computers, you must also specify the name or Internet address of the remote host that is running the MATLAB server (`hdldaemon`).

For more information on choosing TCP/IP socket ports, see "Choosing TCP/IP Socket Ports".

If you run the HDL simulator and MATLAB on the same computer, you have the option of using shared memory for communication. Shared memory is the default mode of communication and takes effect if you do not specify `-socket <tcp_spec>` on the command line.

Note The communication mode that you specify with the `matlabtb` command must match what you specify for the communication mode when you issue the `hdldaemon` command in MATLAB. For more information on modes of communication, see "Communications for HDL Cosimulation". For more information on establishing the MATLAB end of the communication link, see "Starting the HDL Simulator from MATLAB".

`-rising <signal>[, <signal>...]`

Indicates that the application calls the specified MATLAB function on the rising edge (transition from `'0'` to `'1'`) of any of the specified signals. Specify `-rising` with the path names of one or more signals defined as a logic type (`STD_LOGIC`, `BIT`, `X01`, and so on).

For determining signal transition in:

- VHDL: Rising edge is {0 or L} to {1 or H}.
- Verilog: Rising edge is the transition from 0 to x, z, or 1, and from x or z to 1.

Note When specifying signals with the `-rising`, `-falling`, and `-sensitivity` options, specify them in full path name format. If you do not specify a full path name, the command applies the HDL simulator rules to resolve signal specifications.

`-falling <signal>[, <signal>...]`

Indicates that the application calls the specified MATLAB function whenever any of the specified signals experiences a falling edge—changes from `'1'` to `'0'`. Specify `-falling` with the path names of one or more signals defined as a logic type (`STD_LOGIC`, `BIT`, `XO1`, and so on).

For determining signal transition in:

- VHDL: Falling edge is {1 or H} to {0 or L}.
- Verilog: Falling edge is the transition from 1 to x, z, or 0, and from x or z to 0.

Note When specifying signals with the `-rising`, `-falling`, and `-sensitivity` options, specify them in full path name format. If you do not specify a full path name, the command applies the HDL simulator rules to resolve signal specifications.

`-sensitivity <signal>[, <signal>...]`

Indicates that the application calls the specified MATLAB function whenever any of the specified signals changes state. Specify `-sensitivity` with the path names of one or more signals. Signals of any type can appear in the sensitivity list and can be positioned at any level of the HDL design.

If you specify the option with no signals, the interface is sensitive to value changes for all signals.

Note Use of this option for `INOUT` ports can result in double calls.

For example:

```
-sensitivity /randnumgen/dout
```

The MATLAB function executes if the value of `dout` changes.

Note When specifying signals with the `-rising`, `-falling`, and `-sensitivity` options, specify them in full path name format. If you do not specify a full path name, the command applies the HDL simulator rules to resolve signal specifications.

`-mfunc <name>`
: The name of the associated MATLAB function. If you omit this argument, `matlabtb` associates the HDL module instance to a MATLAB function that has the same name as the HDL instance. If you omit this argument and `matlabtb` does not find a MATLAB function with the same name, the command generates an error message.

`-use_instance_obj`
: Instructs the function specified with the argument -mfunc to use an HDL instance object passed by HDL Verifier to the function. This argument has the fields shown in the following table. See "Writing Functions Using the HDL Instance Object" for examples.

Field	Read/Write Access	Description
tnext	Write only	Used to schedule a callback during the set time value. This field is equivalent to old tnext. For example: `hdl_instance_obj.tnext = hdl_instance_obj.tnow + 5e-9` will schedule a callback at time equals 5 nanoseconds from tnow.
userdata	Read/Write	Stores state variables of the current `matlabcp` instance. You can retrieve the variables the next time the callback of this instance is scheduled.

simstatus	Read only	Stores the status of the HDL simulator. The HDL Verifier software sets this field to 'Init' during the first callback for this particular instance and to 'Running' thereafter. simstatus is a read-only property.
		`>> hdl_instance_obj.simstatus`
		`ans=`
		`Init`

instance	Read only	Stores the full path of the Verilog/VHDL instance associated with the callback. instance is a read-only property. The value of this field equals that of the module instance specified with the function call. For example:
		In the HDL simulator:
		`hdlsim> matlabcp osc_top -mfunc oscfilter use_instance_obj`
		In MATLAB:
		`>> hdl_instance_obj.instance`
		`ans=`
		`osc_top`

Field	Read/Write Access	Description

`argument`	Read only	Stores the argument set by the -argument option of `matlabcp`. For example:
		
		`matlabtb osc_top -mfunc oscfilter -use_instance_obj -argument foo`
		
		The link software supports the -argument option only when it is used with -use_instance_obj, otherwise the argument is ignored. argument is a read-only property.
		
		`>> hdl_instance_obj.argument`
		
		`ans=`
		`foo`

`portinfo`	Read only	Stores information about the VHDL and Verilog ports associated with this instance. portinfo is a read-only property, which has a field structure that describes the ports defined for the associated HDL module. For each port, the portinfo structure passes information such as the port's type, direction, and size. For more information on port data, see "Gaining Access to and Applying Port Information". `hdl_instance_obj.portinfo.`*`field1.field2.field3`* **Note** When you use use_instance_obj, you access tscale through the HDL instance object. If you do not use use_instance_obj, you can still access tscale through portinfo.

Field	Read/Write Access	Description

tscale	Read only	Stores the resolution limit (tick) in seconds of the HDL simulator. tscale is a read-only property.
		
		`>> hdl_instance_obj.tscale`
		
		`ans=`
		`1.0000e-009`
		
		Note When you use use_instance_obj, you access tscale through the HDL instance object. If you do not use use_instance_obj, you can still access tscale through portinfo.

tnow	Read only	Stores the current time. tnow is a read-only property. `hdl_instance_obj.tnext = hld_instance_obj.tnow + fastestrate;`

portvalues	Read/Write	Stores the current values of and sets new values for the output and input ports for a `matlabcp` instance. For example:
		
		`>> hdl_instance_obj.portvalues`
		
		`ans =`
		`Read Only Input ports:`
		`clk_enable: []`
		`clk: []`
		`reset: []`
		`Read/Write Output ports:`
		`sine_out: [22x1 char]`

linkmode	Read only	Stores the status of the callback. The HDL Verifier software sets this field to 'testbench' if the callback is

Field	Read/Write Access	Description

		associated with `matlabtb` and 'component' if the callback is associated with `matlabcp`. linkmode is a read-only property.
		
		`>> hdl_instance_obj.linkmode`
		
		`ans=`
		` component`

`-argument`
: Used to pass user-defined arguments from the `matlabtb` instantiation on the HDL side to the MATLAB function callbacks. Supported with `-use_instance_obj` only. See the field listing for argument under the `-use_instance_obj` property.

Examples

The following examples demonstrate some ways you might use the `matlabtb` function.

Using matlabtb with the -socket Argument and Time Parameters

The following command starts the HDL simulator client component of HDL Verifier, associates an instance of the entity, `myfirfilter`, with the MATLAB function `myfirfilter`, and begins a local TCP/IP socket-based test bench session using TCP/IP port 4449. Based on the specified test bench stimuli, `myfirfilter.m` executes 5 nanoseconds from the current time, and then repeatedly every 10 nanoseconds:

```
hdlsim> matlabtb myfirfilter 5 ns -repeat 10 ns -socket 4449
```

Applying Rising Edge Clocks and State Changes with matlabtb

The following command starts the HDL simulator client component of HDL Verifier, and begins a remote TCP/IP socket-based session using remote MATLAB host `compb` and TCP/IP port 4449. Based on the

specified test bench stimuli, `myfirfilter.m` executes 10 nanoseconds from the current time, each time the signal `/top/fclk` experiences a rising edge, and each time the signal `/top/din` changes state.

```
hdlsim> matlabtb /top/myfirfilter 10 ns -rising /top/fclk -sensitivity /top/din
      -socket 4449@computer123
```

Specifying a MATLAB Function Name and Sensitizing Signals with matlabtb

The following command starts the HDL simulator client component of the HDL Verifier software. The `'-mfunc'` option specifies the MATLAB function to connect to and the `'-socket'` option specifies the port number for socket connection mode. `'-sensitivity'` indicates that the test bench session is sensitized to the signal `sine_out`.

```
hdlsim> matlabtb osc_top -sensitivity /osc_top/sine_out
      -socket 4448 -mfunc hosctb
```

Purpose

Call specified MATLAB function once and immediately on behalf of instantiated HDL module

Syntax

```
matlabtbeval <instance> [-socket <tcp_spec>]
[-mfunc <name>]
```

Description

The `matlabtbeval` command has the following characteristics:

- Starts the HDL simulator client component of the HDL Verifier software.
- Associates a specified instance of an HDL design created in the HDL simulator with a MATLAB function.
- Executes the specified MATLAB function once and immediately on behalf of the specified module instance.

This command is issued in the HDL simulator.

Note The `matlabtbeval` command executes the MATLAB function immediately, while `matlabtb` provides several options for scheduling MATLAB function execution.

Notes The communication mode that you specify for `matlabtbeval` must match the communication mode you specified for `hdldaemon` when you established the server connection.

For socket communications, specify the port number you selected for `hdldaemon` when you issue a link request with the `matlabtbeval` command in the HDL simulator.

Arguments

`<instance>`

Specifies the instance of an HDL module that is associated with a MATLAB function. By default, `matlabtbeval` associates the HDL module instance with a MATLAB function that has the

same name as the HDL module instance. For example, if the HDL module instance is `myfirfilter`, `matlabtbeval` associates the HDL module instance with the MATLAB function `myfirfilter`. Alternatively, you can specify a different MATLAB function with the `-mfunc` property.

`-socket <tcp_spec>`

Specifies TCP/IP socket communication for the link between the HDL simulator and MATLAB. For TCP/IP socket communication on a single computer, the `<tcp_spec>` can consist of just a TCP/IP port number or service name (alias). If you are setting up communication between computers, you must also specify the name or Internet address of the remote host.

For more information on choosing TCP/IP socket ports, see "Choosing TCP/IP Socket Ports".

If you run the HDL simulator and MATLAB on the same computer, you have the option of using shared memory for communication. Shared memory is the default mode of communication and takes effect if you do not specify `-socket <tcp-spec>` on the command line.

Note The communication mode that you specify with the `matlabtbeval` command must match what you specify for the communication mode when you call the `hdldaemon` command to start the MATLAB server. For more information on communication modes, see "Communications for HDL Cosimulation". For more information on establishing the MATLAB end of the communication link, see "Starting the HDL Simulator from MATLAB".

`-mfunc <name>`

The name of the associated MATLAB function. If you omit this argument, `matlabtbeval` associates the HDL module instance

with a MATLAB function that has the same name as the HDL module instance.. If you omit this argument and `matlabtbeval` does not find a MATLAB function with the same name, the command displays an error message.

Examples

This example starts the HDL simulator client component of the link software, associates an instance of the module myfirfilter with the function myfirfilter.m, and uses a local TCP/IP socket-based communication link to TCP/IP port 4449 to execute the function myfirfilter.m:

```
hdlsim> matlabtbeval myfirfilter -socket 4449:
```

mvl2dec

Purpose

Convert multivalued logic to decimal

Syntax

```
mvl2dec('mv_logic_string')
mvl2dec('mv_logic_string', signed)
```

Description

`mvl2dec('mv_logic_string')` converts a multivalued logic string to a positive decimal. If *mv_logic_string* contains any character other than `'0'` or `'1'`, `NaN` is returned. *mv_logic_string* must be a vector.

`mvl2dec('mv_logic_string', signed)` converts a multivalued logic string to a positive or a negative decimal. If *signed* is true, this function assumes the first character *mv_logic_string*(1) to be a signed bit of a 2s complement number. If *signed* is missing or false, the multivalued logic string becomes a positive decimal.

Examples

The following function call returns the decimal value 23:

```
>>mvl2dec('010111')
```

The following function call returns `NaN`:

```
>>mvl2dec('xxxxxx')
```

The following function call returns the decimal value -9:

```
>>mvl2dec('10111',true)
```

See Also

`dec2mvl`

Purpose

Start and configure Cadence Incisive simulators for use with HDL Verifier software

Syntax

```
nclaunch('PropertyName', 'PropertyValue'...)
```

Description

`nclaunch('PropertyName', 'PropertyValue'...)` starts the Cadence Incisive simulator for use with the MATLAB and Simulink features of the HDL Verifier software. The first folder in the Cadence Incisive simulator matches your MATLAB current folder if you do not specify an explicit `rundir` parameter.

After you call this function, you can use HDL Verifier functions for the HDL simulator (for example, `hdlsimmatlab`, `hdlsimulink`) to do interactive debug setup.

The property name/property value pair settings allow you to customize the Tcl commands used to start the Cadence Incisive simulator, the `ncsim` executable to be used, the path and name of the Tcl script that stores the start commands, and for Simulink applications, details about the mode of communication to be used by the applications. You must use a property name/property value pair with `nclaunch`.

Name-Value Pair Arguments

hdlsimdir

Specifies the path name to the Cadence Incisive simulator executable to be started.

- `pathname`

  Start a different version of the Cadence Incisive simulator or if the version of the simulator you want to run does not reside on the system path.

  Default: The first version of the simulator that the function finds on the system path.

hdlsimexe

Specifies the name of a Cadence Incisive simulator executable.

- `simexename`

  Custom-built simulator executable.

  Default: `ncsim`

libdir

This property creates an entry in the startup Tcl file that points to the folder with the shared libraries for the Cadence Incisive simulator to communicate with MATLAB when the Cadence Incisive simulator runs on a machine that does not have MATLAB.

- `folder`

  Folder containing MATLAB shared libraries.

libfile

Specifies the library file to use for HDL simulation. If the HDL simulator links other libraries, including SystemC libraries, that were built using a compiler supplied with the HDL simulator, you can specify an alternate library file with this property. See "HDL Verifier Libraries" for versions of the library built using other compilers.

- `library_file_name`

  The particular library file to use for HDL simulation.

  Default: The version of the library file that was built using the same compiler that MATLAB itself uses.

rundir

Specifies the folder containing the HDL simulator executable.

- `dirname`

  Where to run the HDL simulator.

The following conditions apply to this name/value pair:

- If the value of `dirname` is “TEMPDIR”, the function creates a temporary folder in which it runs the HDL simulator.
- If you specify`dirname`and the folder does *not* exist, you will get an error.

Default: The current working folder

runmode

Specifies how to start the HDL simulator.

- `mode`

  This property accepts the following valid values:

  - `'Batch'`: Start the HDL simulator in the background with no window.
  - `'Batch with Xterm'`: Run HDL simulator in an non-interactive Xterm window.
  - `'CLI'`: Start the HDL simulator in an interactive terminal window.
  - `'GUI'`: Start the HDL simulator with the SimVision graphical user interface.

  Default: `'GUI'`

socketsimulink

Specifies TCP/IP socket communication between the Cadence Incisive simulator and Simulink. For shared memory, omit `-socket <tcp-spec>` on the command line.

- `tcp_spec`

  TCP/IP port number or service name (alias)

  Default: Shared memory

starthdlsim

Determines whether the Cadence Incisive simulator is launched.

This function creates a startup Tcl file which contains pointers to MATLAB and Simulink shared libraries. To run the Cadence Incisive simulator manually, see "Starting the HDL Simulator from MATLAB".

- `yes`

  Launches the Cadence Incisive simulator and creates a startup Tcl file.

- `no`

  Does not launch the Cadence Incisive simulator , but still creates a startup Tcl file.

  Default: `yes`

startupfile

Specify the name and location of the Tcl script generated by `nclaunch`. The generated Tcl script, when executed, compiles and launches the HDL simulator. You can edit and use the generated file in a regular shell outside of MATLAB. For example:

```
sh> tclsh compile_and_launch.tcl
```

- `pathname`

  Filename and path for generated Tcl script. If the file name already exists on the specified path, that file's contents are overwritten.

  Default: Generates a filename of `compile_and_launch.tcl` in the folder specified by `rundir`.

tclstart

Specifies one or more Tcl commands to execute before the Cadence Incisive simulator launches. You must specify at least one command; otherwise, no action occurs.

- `tcl_commands`

A command string or a cell array of command strings.

Note You must type `exec` in front of non-Tcl system shell commands. For example:

```
exec -ncverilog -c +access+rw +linedebug top.v
hdlsimulink -gui work.top
```

Examples

Start Cosimulation Session with Simulink

Compile design and start Simulink.

```
nclaunch('tclstart',{'exec ncverilog -c +access+rw +linedebug top.v','hdlsimulink...
     -gui work.top'},'socketsimulink','4449','rundir', '/proj');
```

In this example, `nclaunch` performs the following:

- Compiles the design top.v: `exec ncverilog -c +access+rw +linedebug top.v`.
- Starts Simulink with the GUI from the *`proj`* folder with the model loaded: `hdlsimulink -gui work.top` and `'rundir', '/proj'`.
- Instructs Simulink to communicate with the HDL Verifier interface on socket port 4449: `` `socketsimulink','4449' ``.

All of these commands are specified in a single string as the property value to `tclstart`.

Create Tcl Script to Start HDL Simulator

Create a Tcl script to start the HDL simulator from a Tcl shell using `nclaunch`.

Specify the name of the Tcl script and the command(s) it includes as parameters to `nclaunch`:

```
nclaunch (`tclstart', `xxx', `startupfile', `mytclscript', `starthdlsim', `yes')
```

In this example, a Tcl script is created and the command to start the HDL simulator is included. The startup Tcl file is named "mytclscript".

Execute the script in a Tcl shell:

```
shell> tclsh mytclscript
```

This starts the HDL simulator.

Execute Multiple Tcl Commands When Launching Cosimulation Connection

Build a sequence of Tcl commands that are then executed in a Tcl shell, after calling `nclaunch` from MATLAB.

Assign Tcl command values to the tclcmd parameter of `nclaunch`:

```
tclcmd{1} = 'exec ncvlog vlogtestbench_top.v'
tclcmd{2} = 'exec ncelab -access +wc vlogtestbench_top'
tclcmd{3} = ['hdlsimmatlab -gui vlogtestbench_top ' '-input "{@matlabcp...
     vlogtestbench_top.u_matlab_component -mfunc vlogmatlabc...
     -socket 32864}" ' '-input "{@run 50}"']

tclcmd =

    'exec ncvlog vlogtestbench_top.v'    'exec ncelab -access +wc vlogtestbench_top'


tclcmd =

    'exec ncvlog vlogtestbench_top.v'    'exec ncelab -access +wc vlogtestbench_top'


tclcmd =

    [1x31 char]    [1x41 char]    [1x145 char]
```

- `tclcmd{1}` compiles `vlogtestbench_top`.
- `tclcmd{2}` elaborates the model.
- `tclcmd{3}` calls `hdlsimmatlab` in `gui` mode and loads the elaborated `vlogtestbench_top` in the simulator.

Issue the `nclaunch` command, passing the tclcmd variable just set:

```
nclaunch('hdlsimdir', 'local.IUS.glnx.tools.bin', 'tclstart',tclcmd);
```

In this example, the `nclaunch` launches the following tasks through the Tcl commands assigned in tclcmd:

- Executes the arguments being passed with `-input` (`matlabtb` and `run`) in the ncsim Tcl shell.
- Issues a call to `matlabcp`, which associates the function `vlogmatlabc` to the module instance `u_matlab_component`.
- Assumes that the `hdldaemon` in MATLAB is listening on port 32864
- Instructs the `run` function to run 50 resolution units (ticks).

nomatlabtb

Purpose

End active MATLAB test bench and MATLAB component sessions

Syntax

```
nomatlabtb
```

Description

The `nomatlabtb` command ends all active MATLAB test bench and MATLAB component sessions that were previously initiated by matlabtb or matlabcp commands.

This command is issued in the HDL simulator.

Note This command should be called before shutting down `hdldaemon` or `hdldaemon` will block shutdown until the call occurs.

Examples

The following command ends all MATLAB test bench and MATLAB component sessions:

```
hdlsim> nomatlabtb
```

See Also

`matlabtb | matlabcp`

Purpose

Send HDL simulator event and process IDs to MATLAB server

Syntax

```
notifyMatlabServer EventID -socket tcp-spec
```

Description

`notifyMatlabServer` *`EventID`* `-socket` *`tcp-spec`* sends the HDL simulator event ID and process identification (PID) to the MATLAB server (`hdldaemon`) using the specified connection methods (socket or shared memory). For MATLAB to receive this message, hdldaemon must be running with the same communication mode as specified with the `notifyMatlabServer` command. The event ID and the PID queue in hdldaemon. `notifyMatlabServer` is often used in conjunction with `waitForHdlClient` to make sure the HDL simulator is ready to begin or continue processing.

This command issues in the HDL simulator.

Input Arguments

EventID

Specifies the event ID to be sent to hdldaemon. The ID requires a positive number less than the maximum value of 32-bit signed integer. This parameter contains the event ID expected by the command `waitForHdlClient` in MATLAB.

Default: 1

socket tcp_spec

Specifies that TCP/IP socket communication be used for the link between the HDL simulator and MATLAB. For TCP/IP socket communication on a single computer, *`tcp_spec`* requires either a TCP/IP port number or service name (alias). To set up communication between computers, you must also specify the name or Internet address of the remote host that is running the MATLAB server (`hdldaemon`).

When you omit the `socket` option, MATLAB and the HDL simulator use shared memory communication.

Examples

In MATLAB, use the function `waitForHdlClient` to verify whether the HDL simulator event ID has been received. In the following example, the function returns the HDL Simulator PID if EventID = 5 is received within 100 seconds. If a time-out occurs, the function returns –1.

```
>> hdldaemon('socket',5002);
...
>> hdlpid = waitForHdlClient(100,5);
```

In the HDL simulator, issue the `notifyMatlabServer` command to send event ID 5 to `hdldaemon` running on the same machine using TCP/IP socket port 5002.

```
>> notifyMatlabServer 5 -socket 5002
```

See Also

`waitForHdlClient`

Purpose

Block cosimulation until HDL simulator is ready for simulation

Syntax

```
pingHdlSim(timeout)
pingHdlSim(timeout, 'portnumber')
pingHdlSim(timeout, 'portnumber', 'hostname')
```

Description

`pingHdlSim(timeout)` blocks cosimulation by not returning until the HDL server loads or until the specified time-out occurs. `pingHdlSim` returns the process ID of the HDL simulator or -1 if a time-out occurs. You must enter a time-out value. You may find this function useful if you are trying to automate a cosimulation and need to know that the HDL server has loaded before your script continues the simulation.

`pingHdlSim(timeout, 'portnumber')` tries to connect to the local host on port *portnumber* and times out after *timeout* seconds you specify.

`pingHdlSim(timeout, 'portnumber', 'hostname')` tries to connect to the host *hostname* on port *portname*. It times out after *timeout* seconds you specify.

Examples

The following function call blocks further cosimulation until the HDL server loads or until 30 seconds have passed:

```
>>pingHdlSim(30)
```

If the server loads within 30 seconds, `pingHdlSim` returns the process ID. If it does not, `pingHdlSim` returns -1.

The following function call blocks further cosimulation on port 5678 until the HDL server loads or until 20 seconds have passed:

```
>>pingHdlSim(20, '5678')
```

The following function call blocks further cosimulation on port 5678 on host name `msuser` until the HDL server loads or until 20 seconds pass:

```
>>pingHdlSim(20, '5678', 'msuser')
```

setupxilinxtools

Purpose

Configure MATLAB environment for use with Xilinx FPGA Automation and Filter Design HDL Coder

Syntax

```
setupxilinxtools
setupxilinxtools(isepath)
```

Description

`setupxilinxtools` performs the following tasks so that your environment is optimally set up to use Xilinx® FPGA Automation:

- Verifies that the XILINX system environment variable is defined and points to a valid Xilinx ISE installation
- Checks whether your platform and Xilinx ISE version is supported for FPGA Automation
- Adds any paths to your MATLAB search path for using Xilinx FPGA Automation.

`setupxilinxtools(isepath)` performs the same validations as `setupxilinxtools` and also uses the value in *`isepath`* to set the XILINX environment variable. If *`isepath`* points to a valid ISE installation, `setupxilinxtools(isepath)` also adds that ISE installation on the system path.

All changes to system environment variables, system path, or MATLAB search path using `setupxilinxtools(...)` apply to the current MATLAB session only.

FIL Setup If you want to set up your environment for FPGA-in-the-Loop, use the `hdlsetuptoolpath` function instead. Enter `help hdlsetuptoolpath` at the MATLAB command prompt for more information.

Examples

Enter the following command at the MATLAB command prompt:

```
>>setupxilinxtools
```

Enter the following command at the MATLAB command prompt, substituting the value in *isepath* below with a valid ISE installation for your machine:

```
>>setupxilinxtools('C:\Xilinx\12.1\ISE')
```

tclHdlSim

Purpose

Execute Tcl command in Incisive or ModelSim simulator

Syntax

```
tclHdlSim(tclCmd)
tclHdlSim(tclCmd,'portNumber')
tclHdlSim(tclCmd, 'portnumber', 'hostname')
```

Description

`tclHdlSim(tclCmd)` executes a Tcl command on the Incisive or ModelSim simulator using a shared connection during a Simulink cosimulation session.

`tclHdlSim(tclCmd,'portNumber')` executes a Tcl command on the Incisive or ModelSim simulator by connecting to the local host on port *portNumber*.

`tclHdlSim(tclCmd, 'portnumber', 'hostname')` executes a Tcl command on the Incisive or ModelSim simulator by connecting to the host *hostname* on port *portname*.

The Incisive or ModelSim simulator must be connected to MATLAB and Simulink using the HDL Verifier software for this function to work (see either `vsimulink` or `hdlsimulink`).

You may specify any valid Tcl command string. The Tcl command string you specify cannot include commands that load an HDL simulator project or modify simulator state. For example, the string cannot include commands such as `start`, `stop`, or `restart` (for ModelSim) or `run`, `stop`, or `reset` (for Incisive).

To execute a Tcl command on the Incisive or ModelSim simulator during a MATLAB cosimulation session, use `hdldaemon('tclcmd','command')`.

Examples

The following function call displays a message in the HDL simulator command window using port 5678 on host name msuser:

```
>>tclHdlSim('puts "Done"', '5678', 'msuser')
```

See Also

`hdldaemon` | `nclaunch` | `vsim`

Purpose

Start and configure ModelSim for use with HDL Verifier

Syntax

```
vsim('PropertyName', 'PropertyValue'...)
```

Description

`vsim('PropertyName', 'PropertyValue'...)` starts and configures the ModelSim simulator (`vsim`) for use with the MATLAB and Simulink features of HDL Verifier. The first folder in ModelSim matches your MATLAB current folder.

After you call this function, you can use HDL Verifier functions for the HDL simulator (for example, `vsimmatlab`, `vsimulink`) to perform the following actions:

- Load instances of VHDL entities or Verilog modules for simulations that use MATLAB for verification
- Load instances of VHDL entities or Verilog modules for simulations that use Simulink for cosimulation

The property name/property value pair settings allow you to customize the Tcl commands used to start ModelSim, the `vsim` executable to be used, the path and name of the DO file that stores the start commands, and for Simulink applications, details about the mode of communication to be used by the applications.

Tip Use `pingHdlSim` to add a pause between the call to `vsim` and the call to actually run the simulation when you are attempting to automate the cosimulation.

Property Name/Property Value Pairs

hdlsimdir

Specifies the path name to the Cadence Incisive simulator executable to be started.

- `pathname`

Start a different version of the Cadence Incisive simulator or if the version of the simulator you want to run does not reside on the system path.

Default: The first version of the simulator that the function finds on the system path.

libdir

Creates an entry in the startup Tcl file that points to the folder containing MATLAB library files

- `folder`

  Folder containing the libraries for ModelSim to communicate with MATLAB when ModelSim runs on a machine that does not have MATLAB.

libfile

Specifies a particular library file.

- `library_file_name`

  . This value defaults to the version of the library file that was built using the same compiler that MATLAB itself uses. If the HDL simulator links other libraries, including SystemC libraries, that were built using a compiler supplied with the HDL simulator, you can specify an alternate library file with this property. See “HDL Verifier Libraries” for versions of the library built using other compilers.

pingTimeout

Time to wait, in seconds, for the HDL simulator to start.

- `seconds`

  Specify 0 (the default) to immediately return without waiting.

rundir

Specifies where to run ModelSim.

- `dirname`

  By default, the function uses the current working folder.

  The following conditions apply to this name/value pair:

  - If the value of `dirname` is "TEMPDIR", the function creates a temporary folder in which it runs ModelSim.
  - If you specify `dirname` and the folder does *not* exist, you will get an error.

runmode

Specifies how to start the HDL simulator.

- `mode`

  You can set run mode to the following valid values:

  - `'Batch'`: Start the HDL simulator in the background with no window (Linux) or in a non-interactive command window (Windows).
  - `'CLI'`: Start the HDL simulator in an interactive terminal window.
  - `'GUI'`: Start the HDL simulator with the ModelSim graphical user interface.

  This value defaults to `'GUI'`.

socketsimulink

Specifies TCP/IP socket communication for links between ModelSim and Simulink.

- `tcp_spec`

  For TCP/IP socket communication on a single computing system, the `tcp_spec` can consist of just a TCP/IP port number or service name. If you are setting up communication between computing systems, you must also specify the name or Internet address of the remote host.

For more information on choosing TCP/IP socket ports, see "Choosing TCP/IP Socket Ports"

If ModelSim and Simulink run on the same computing system, you have the option of using shared memory for communication. Shared memory is the default mode of communication and takes effect if you do not specify `-socket <tcp-spec>` on the command line.

Note The function applies the communication mode specified by this property to all invocations of Simulink from ModelSim.

---

startms

Determines whether ModelSim will launch from `vsim`.

- `yes | no`

  This property defaults to `yes`, which launches ModelSim and creates a startup Tcl file. If `startms` is set to `no`, ModelSim does not launch, but the HDL simulator still creates a startup Tcl file.

  This startup Tcl file contains pointers to MATLAB libraries. To run ModelSim on a machine without MATLAB, copy the startup Tcl file and MATLAB library files to the remote machine and start ModelSim manually. See "HDL Verifier Libraries".

startupfile

Specifies Tcl script for startup.

- `pathname`

  Each invocation of `vsim` creates a Tcl script that, when executed, compiles and launches the HDL simulator. By default, this function generates the filename of `compile_and_launch.tcl` in the folder specified by `rundir`.. With this property, you can specify the name and location of the generated Tcl script. If the file name already exists, that file's contents are overwritten. You can edit and use the generated file in a regular shell outside of MATLAB. For example:

```
sh> vsim -gui -do compile_and_launch.tcl
```

tclstart

Specifies one or more Tcl commands to execute after ModelSim launches.

- `tcl_commands`

  Specify a command string or a cell array of command strings.

vsimdir

Specifies the path name to the ModelSim simulator executable (`vsim.exe`) to be started.

- `pathname`

  By default, the function uses the first version of `vsim.exe` that it finds on the system path (defined by the `path` variable) . Use this option to start different versions of the ModelSim simulator or if the version of the simulator you want to run does not reside on the system path.

Examples

The following function call sequence changes the folder location to `VHDLproj` and then calls the function `vsim`. Because the call to `vsim` omits the `'vsimdir'` and `'startupfile'` properties, `vsim` uses the default `vsim` executable and creates a temporary DO file in a temporary folder. The `'tclstart'` property specifies a Tcl command that loads an instance of a VHDL entity for MATLAB verification:

- The `vsimmatlab` command loads an instance of the VHDL entity `parse` in the library `work` for MATLAB verification.
- The `matlabtb` command begins the test bench session for an instance of entity `parse`, using TCP/IP socket communication on port 4449 and a test bench timing value of 10 ns.

```
>>cd VHDLproj  % Change folder to ModelSim project folder
>>vsim('tclstart','vsimmatlab work.parse; matlabtb parse 10 ns -socket 4449')
```

The following function call sequence changes the folder location to `VHDLproj` and then calls the function `vsim`.

- Because the call to `vsim` omits the `'vsimdir'` and `'startupfile'` properties, `vsim` uses the default `vsim` executable and creates a DO file in a temporary folder.
- The `'tclstart'` property specifies a Tcl command that loads the VHDL entity `parse` in the library `work` for cosimulation between `vsim` and Simulink.
- The `'socketsimulink'` property specifies that TCP/IP socket communication on the same computer is to be used for links between Simulink and ModelSim, using socket port 4449.

```
>>cd VHDLproj  % Change folder to ModelSim project folder
>>vsim('tclstart','vsimulink work.parse','socketsimulink','4449')
```

Purpose

Load instantiated HDL module for verification with ModelSim and MATLAB

Syntax

```
vsimmatlab <instance> [<vsim_args>]
```

Description

The `vsimmatlab` command loads the specified instance of an HDL module for verification and sets up ModelSim so it can establish a communication link with MATLAB. ModelSim opens a simulation workspace and displays a series of messages in the command window as it loads the HDL module's packages and architectures.

This command is generally issued in the HDL simulator. It also may be run from the HDL simulator prompt or from a Tcl script shell (`tclsh`).

Arguments

`<instance>`
: Specifies the instance of an HDL module to load for verification.

`<vsim_args>`
: Specifies one or more ModelSim `vsim` command arguments. For details, see the description of `vsim` in the ModelSim documentation.

Examples

The following command loads the HDL module instance `parse` from library `work` for verification and sets up ModelSim so it can establish a communication link with MATLAB:

```
ModelSim> vsimmatlab work.parse
```

vsimulink

Purpose

Load instantiated HDL module for cosimulation with ModelSim and Simulink

Syntax

```
vsimulink instance> [<vsim_args>]
```

Description

The `vsimulink` command loads the specified instance of an HDL module for cosimulation and sets up ModelSim so it can establish a communication link with Simulink. ModelSim opens a simulation workspace and displays a series of messages in the command window as it loads the HDL module's packages and architectures.

This command is issued in the HDL simulator. The communication mode is determined by the call to `vsim`, which must be issued before you call `vsimulink`.

Argument

`<instance>`
: Specifies the instance of an HDL module to load for cosimulation.

`<vsim_args>`
: Specifies one or more ModelSim `vsim` command arguments. For details, see the description of `vsim` in the ModelSim documentation. Do not issue a command such as `vsim < command.do` with this parameter.

Examples

The following command loads the HDL module instance `parse` from library `work` for cosimulation and sets up ModelSim so it can establish a communication link with Simulink:

```
ModelSim> vsimulink work.parse
```

Purpose

Wait until specified event ID is obtained or time-out occurs

Syntax

```
waitForHdlClient(TimeOut,EventID)
waitForHdlClient(TimeOut)
waitForHdlClient
output = waitForHdlClient(TimeOut,EventID)
```

Description

`waitForHdlClient(`*`TimeOut`*`,`*`EventID`*`)` waits for the expected HDL simulator event ID to arrive at the MATLAB server (`hdldaemon`) before processing continues. If the expected event ID arrives before the number of seconds specified by the *`TimeOut`* parameter, the value returned by the HDL simulator is the HDL simulator process identification (PID). Otherwise, the returned value is –1.

`waitForHdlClient(`*`TimeOut`*`)` waits for EventID = 1 for *`TimeOut`* seconds.

`waitForHdlClient` waits for EventID = 1 for 60 seconds.

`output` `= waitForHdlClient(`*`TimeOut`*`,`*`EventID`*`)` returns the process identification (PID) in *`output`*. Although you are not required to provide an output variable, MATLAB returns an error if a time-out occurs and the output argument is not specified.

Input Arguments

TimeOut

Number of seconds to wait for a response from the HDL simulator

EventID

The HDL simulator event ID. *`EventID`* must be a positive number less than the maximum value of a 32-bit signed integer. The value should match the event ID sent by the `notifyMatlabServer` command in the HDL simulator.

`EventID` can be either a scalar or vector value. If *`EventID`* is a vector, the function return a value only if all elements of the vector have been collected or if a time-out occurs. The returned output value is the same size as the event ID, and each element of the output variable is the

detected PID of the HDL simulator that sends the corresponding event ID element.

Output Arguments

output

Output variable for holding returned value from call to waitForHdlClient. Contains either the HDL simulator process identification (PID) or –1 if an error occurs.

Examples

Wait for event ID 2 for 120 seconds.

```
>> hdlpid = waitForHdlClient(120, 2);
```

See Also

`notifyMatlabServer`

Index

H

I

M

N

O

P

R

S

T

V

W